

An Ubiquitous Multi-Agent Mobile Platform for Distributed Crowd Sensing and Social Mining

Stefan Bosse*

University of Bremen

Department of Mathematics & Computer Science

ISIS Scientific Centre for Sensorial Materials

Bremen, Germany

*** Presenting Author**

Evangelos Pournaras

ETH Zürich

Chair of Sociology

Modeling and Simulation

Zürich, Switzerland

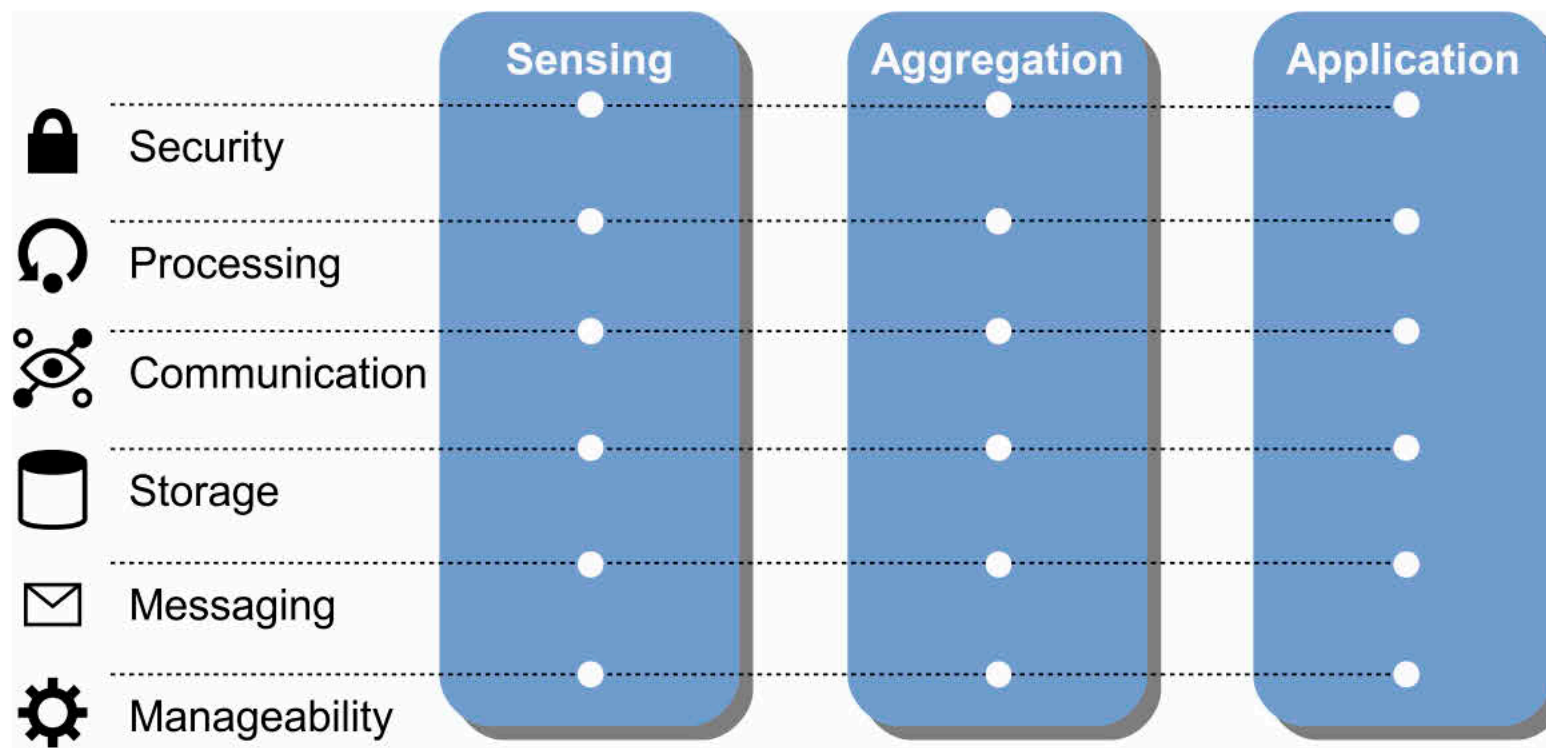
Overview

- A. Ubiquitous Computing and Crowd Sourcing
- B. Virtual Sensors and Agents
- C. Nervousnet: Crowd Sourcing Framework
- D. JAM: The JavaScript Agent Machine Platform
- E. Case Study and Simulation: Crowd Sourcing with Agents
- F. Conclusions

A. Ubiquitous Computing and Crowd Sourcing

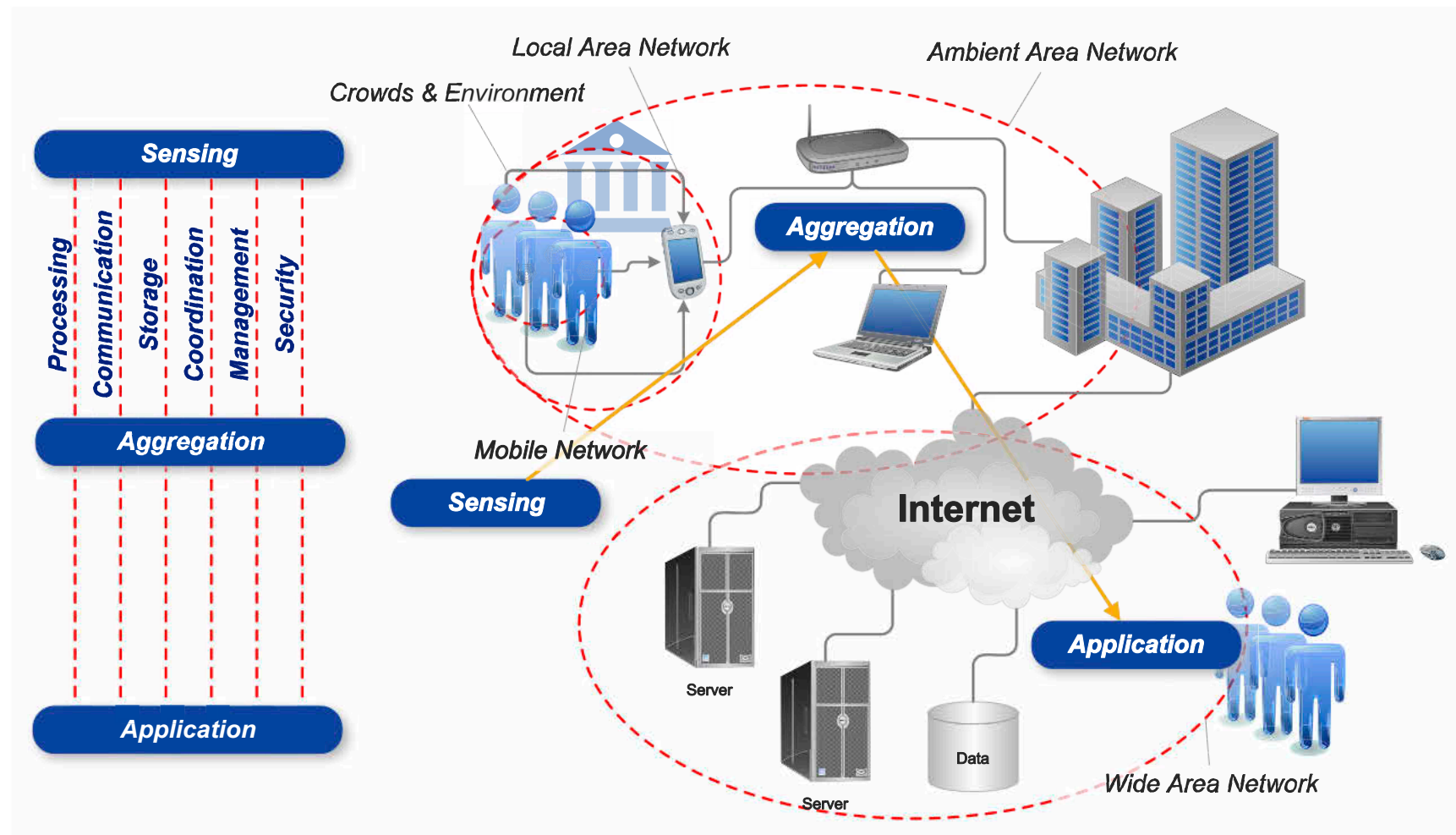
Sensing Process

- » A sensing system consists of three vertical functional layers:
 - » Sensing, Aggregation, Application ➡ [SAA Architecture](#)
- » All functional layers consist of six horizontal operational layers:
 - » Security, Processing, Communication, Storage, Messaging, Manageability



Sensing Process (cont.)

Sensing \Rightarrow **Aggregation** \Rightarrow **Application Layers: Crowd Sensing and Sourcing**



Mobile Networks

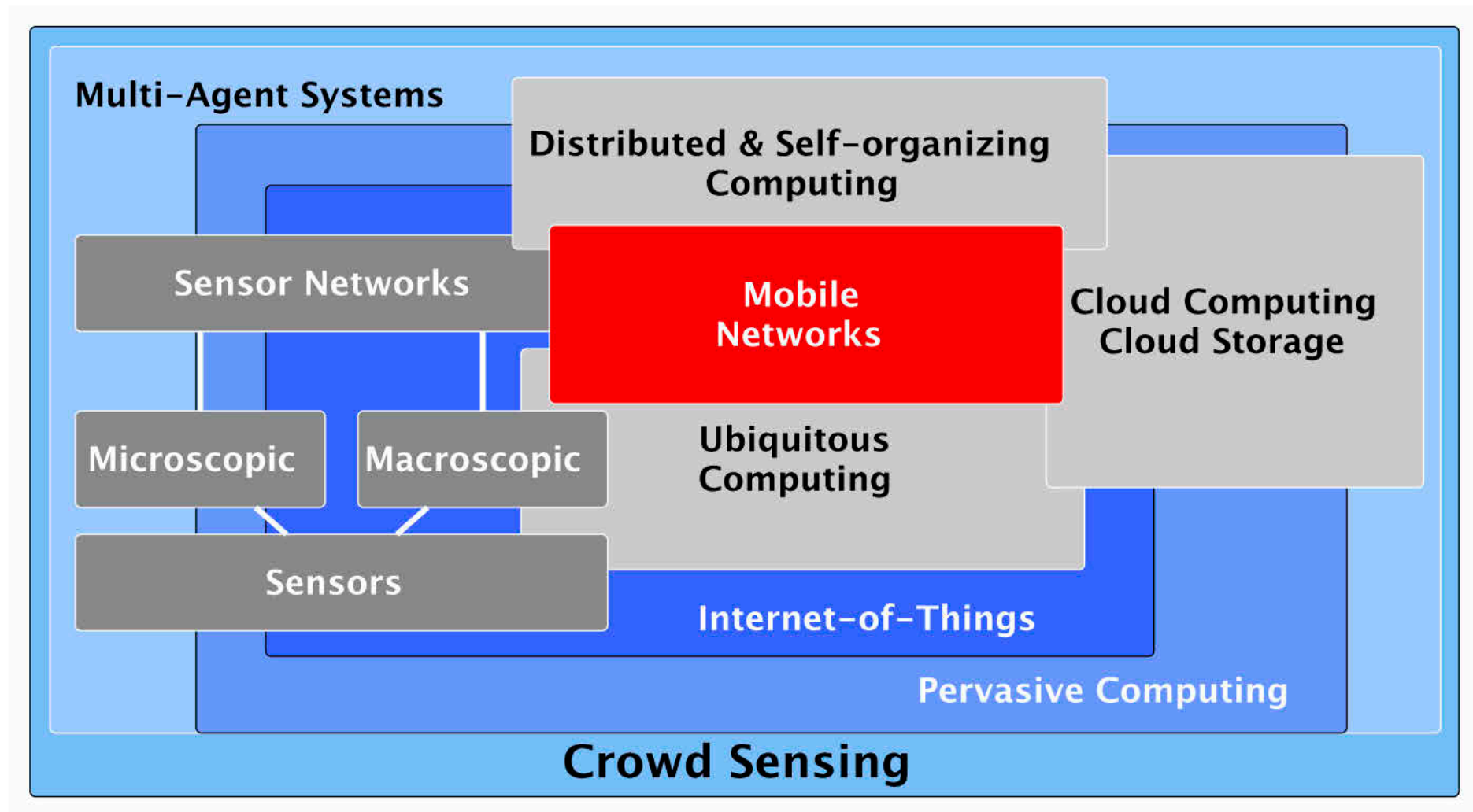
- » Mobile networks, wearable devices, and the Internet-of-Things get more and more pervasive in today's digital society
- » Billions of devices can contribute to pervasive and ubiquitous computing, forming one big machine

Constraints

- » Dynamic Network Structures (in temporal and spatial domain)
- » Connectivity
 - » Ad-hoc
 - » Unicast: Point-to-Point
 - » Multicast (groups)
 - » Internet (virtual networking)
- » Heterogeneous Devices (different processing capabilities, networking, ..)
- » Heterogeneous and unreliable Sensors (not calibrated, noise, ..)

Ubiquitous Computing

The Future of Ubiquitous and Pervasive Computing: Crowd and Thing Sensing



Future ICT

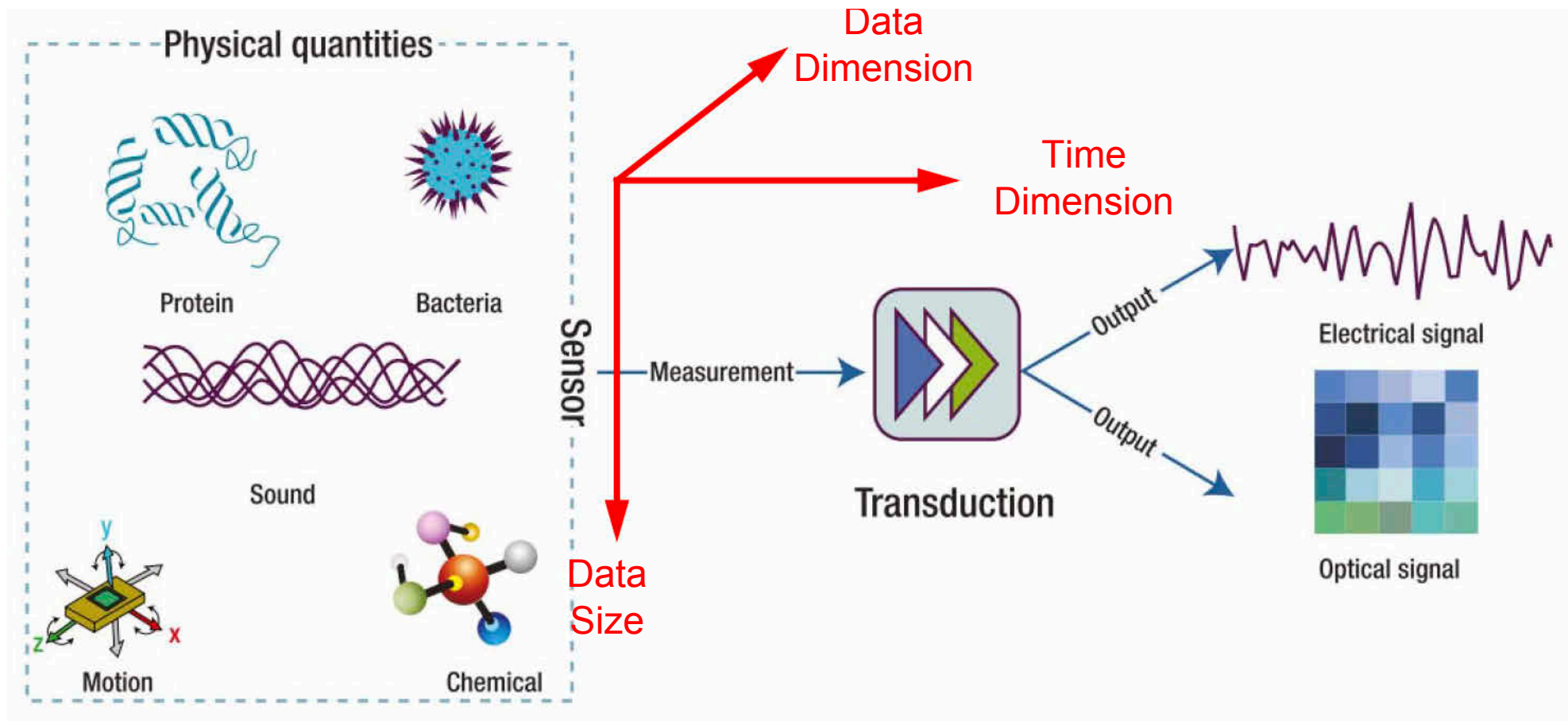
- » New Information and Communication Technologies are required!
- » One unified approach \Rightarrow Deployment on all functional/operationsl layers and host platforms
- » Features and Requirements:
 - » Robustness + Reliability
 - » Soft Computing / Computational Intelligence \Rightarrow Distributed Intelligence
 - » Self-*: Self-Organization / Self-Adaptivity / Self-Awareness
 - » Processing on heterogeneous host platforms (mobile, embedded, server)
 - » Learning

Multi-Agent Systems can offer all these features and fulfil the requirements!

B. Virtual Sensors and Agents

Physical Sensors

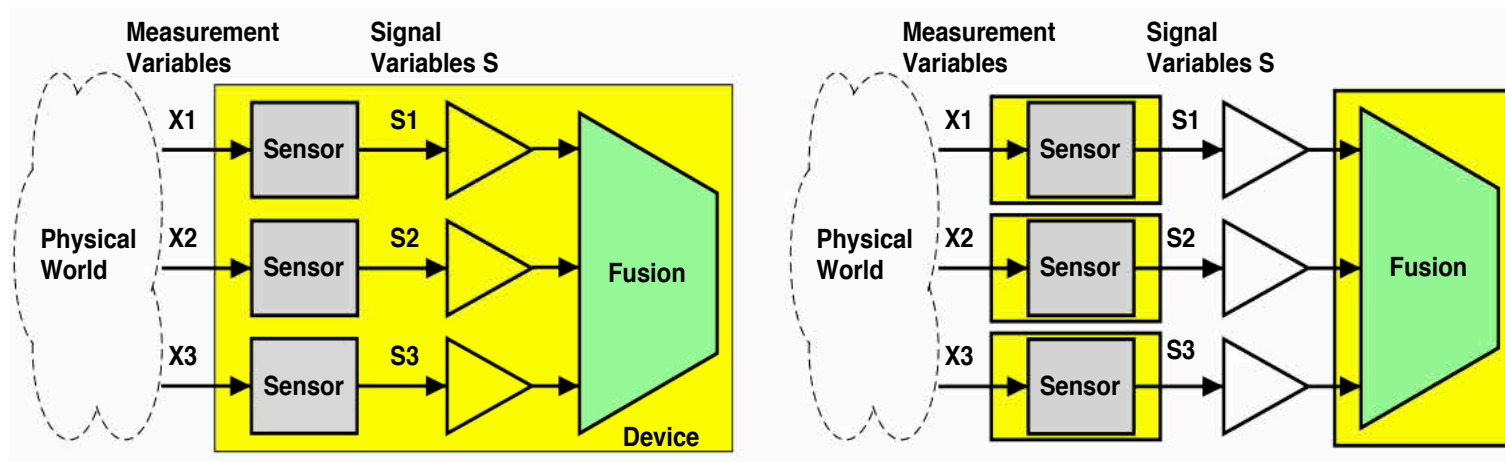
- » Broad diversity of Sensors and Sensor Information for Processing
[kind, size, dimension]



[McGrath et al., ST, 2014]

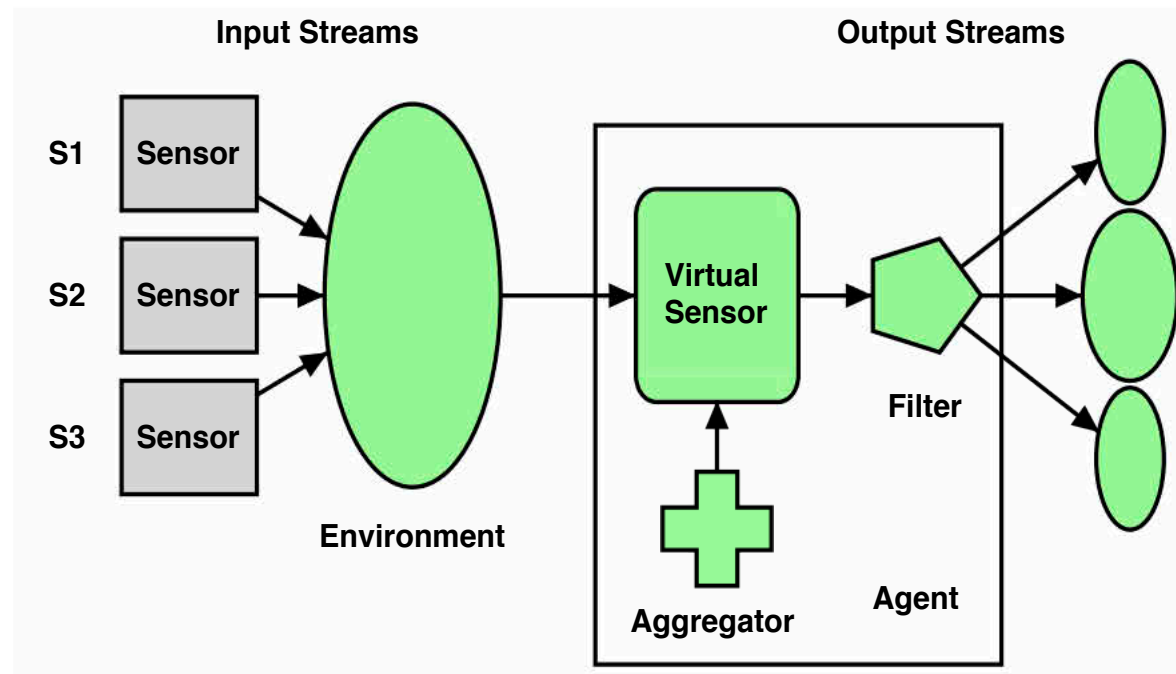
Sensor Fusion

- » Physical sensors are unreliable and noisy depending on device class:
 - » Measuring Devices
 - » Consumer Devices
- » Fusion of multiple sensors can increase accuracy and certainty by using:
 - » Sensors measuring the same physical quantity (mean filter)
 - » Sensors measuring different physical quantities (e.g., strain + temperature)
 - » Distributed correlated Sensors in a region
 - » Distributed uncorrelated but tagged Sensors (spatially/user related)



Virtual Sensors and Agents

- » The environment of a sensor is a set of input streams of data generated from physical or virtual sensors.
- » The environment defines the context within the virtual sensor operates.
- » The aggregator processes the input streams ➡ Fusion
- » The filter produces a set of output streams
- » ➡ Agents can represent and implement virtual sensors!

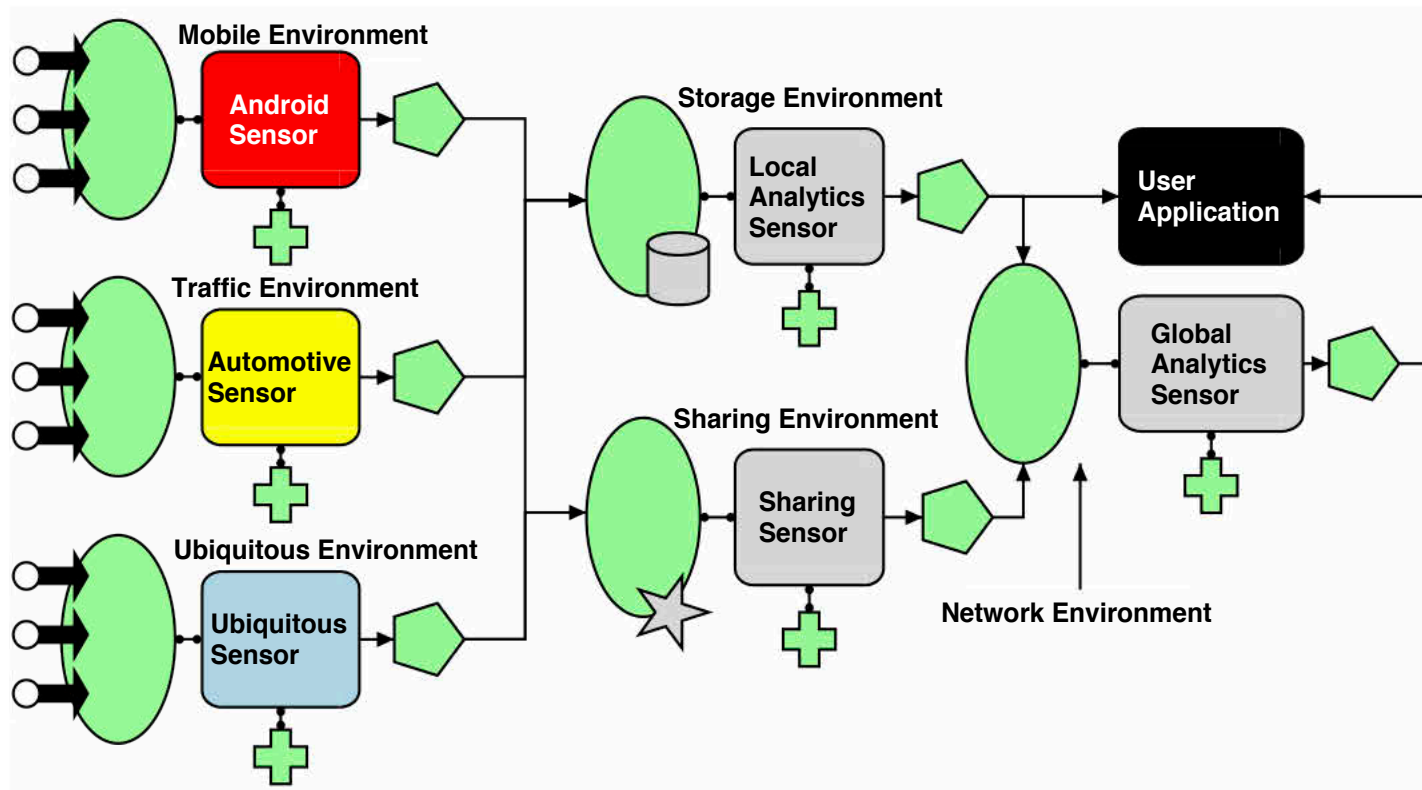


C. NervousNet: Crowd Sourcing Framework

NervousNet

NervousNet: The Planetary Nervous System (Pournaras)

- » Hierarchical Structure based on Virtual Sensors featuring:
 - » SAA-Architecture, Privacy Control, Storage, Com., Local & Global Analytics
 - » Heterogeneous Host Platforms (Mobile, Embedded, Server)



NervousNet: The Agent Approach

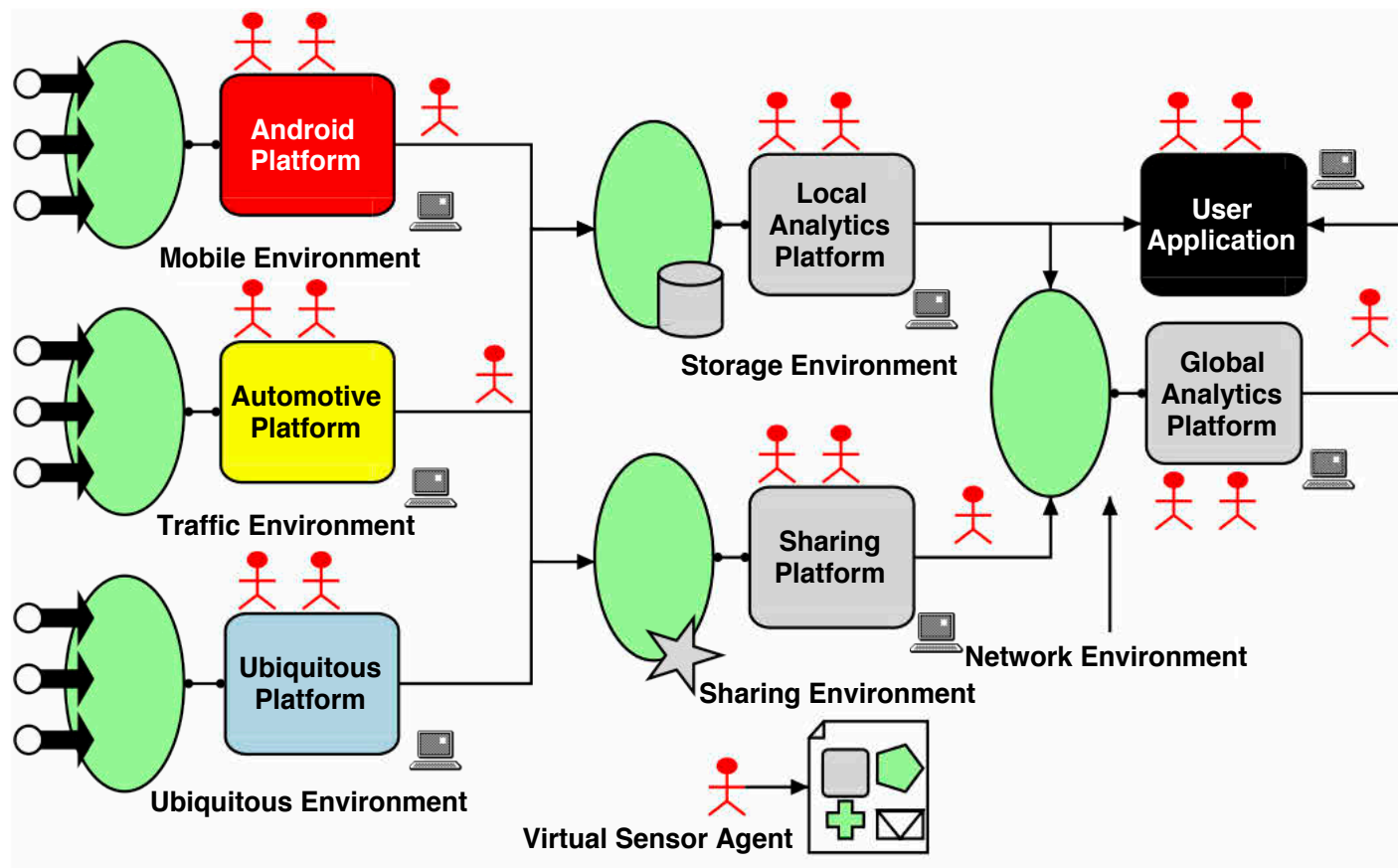
- » Available Sensors:
 - ⟨ *Position, Connectivity, Context, Temperature, Acceleration, Sound, Light ..* ⟩
- » Currently the NervousNet software must be installed on all devices:
 - » Strong dependency on underlying platform and communication network
 - » Difficult to maintain / update; binary releases for each device/platform ..
 - » One Virtual Sensor is one device/program & Client-Server Architecture

Solution:

- » Agents as Virtual Sensors can cover the entire SAA architecture:
 - » Agents are loosely coupled to platform and network infrastructure
 - ▢▢▢▢▢ Deployment in heterogeneous environments
 - » One Virtual Sensor is one Agent
 - ▢▢▢▢▢ Multiple VS on one device/node
 - » Mobile Agents carry their program and behaviour
 - ▢▢▢▢▢ Simplifies updating and adaptation

NervousNet: The Agent Approach (cont.)

- » Agents implement the sensor data aggregator and filter function
- » Agents are fusion, storage, and communication/transport entities
- » Agent processing is encapsulated by a unified Agent Processing Platform



D. JAM: The JavaScript Agent Machine Platform

JavaScript

- » Deployment of agents in strong heterogeneous environments requires an unified and portable modelling and programming language!
- » Agents require: Mobility \Rightarrow Code Migration; Adaptivity \Rightarrow Code Morphing
- » Commonly **JAVA** is used:
 - ✗ Strong coupling to processing platform and API
 - ✗ No code mobility without expensive transformation; requires Compiler
 - ✗ Code cannot be modified at run-time (no code morphing capability)
- » WEB programming uses **JavaScript**:
 - ✓ Loosely coupled to processing platform and API
 - ✓ Can be processed in text form
 - ✓ Code-Text duality (eases code mobility) provided by platform
 - ✓ Code can be modified at run-time (code morphing capability)
- » JavaScript platform available on all devices (mobile, embedded, server)

AgentJS: Agent JavaScript

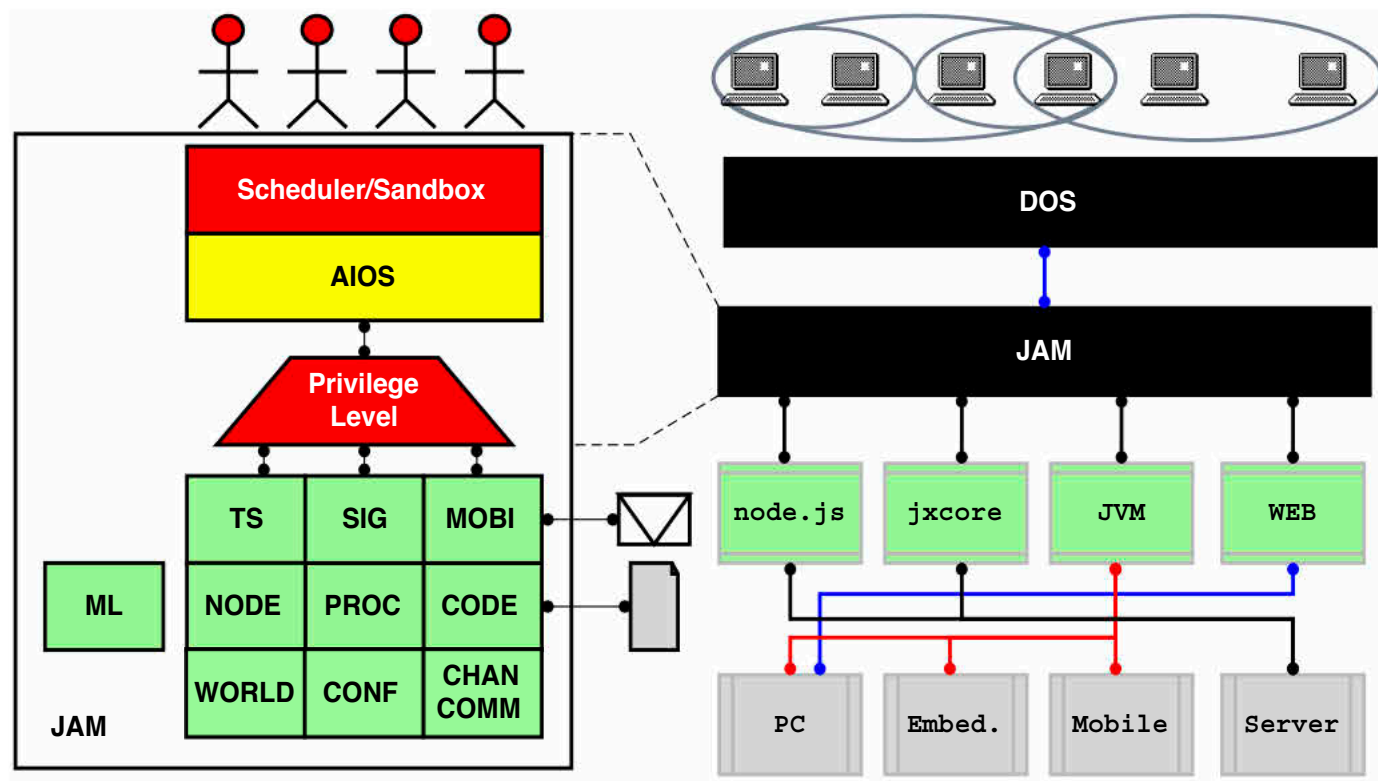
- » Agent behaviour modelling: **Activity-Transition Graphs** & Classes
- » Agent Interaction: Tuple Spaces, Signals
- » Platform access via privilege level protected **AIOS**: Agent I/O System
- » Agent execution in a sandbox; Migration of textual process snapshots

```
function explorer(dir) {  
  this.v=0;  
  this.dir=dir;  
  this.act = {  
    init: function () { if (this.dir==DIR.ORIGIN) this.dir=DIR.NORTH },  
    migrate: function () { moveto(this.dir) },  
    percept: function () { in(['SENSOR',_],function (t) {this.v=t[1]}) },  
    deliver: function () { out(['SENSOR',this.v]) },  
    end: function () {kill(me)}  
  }  
  this.trans = {  
    init: migrate,  
    percept: function () { this.v>10?migrate:deliver },  
    ..  
  }
```

JAM: JavaScript Agent Machine

» Modular Approach

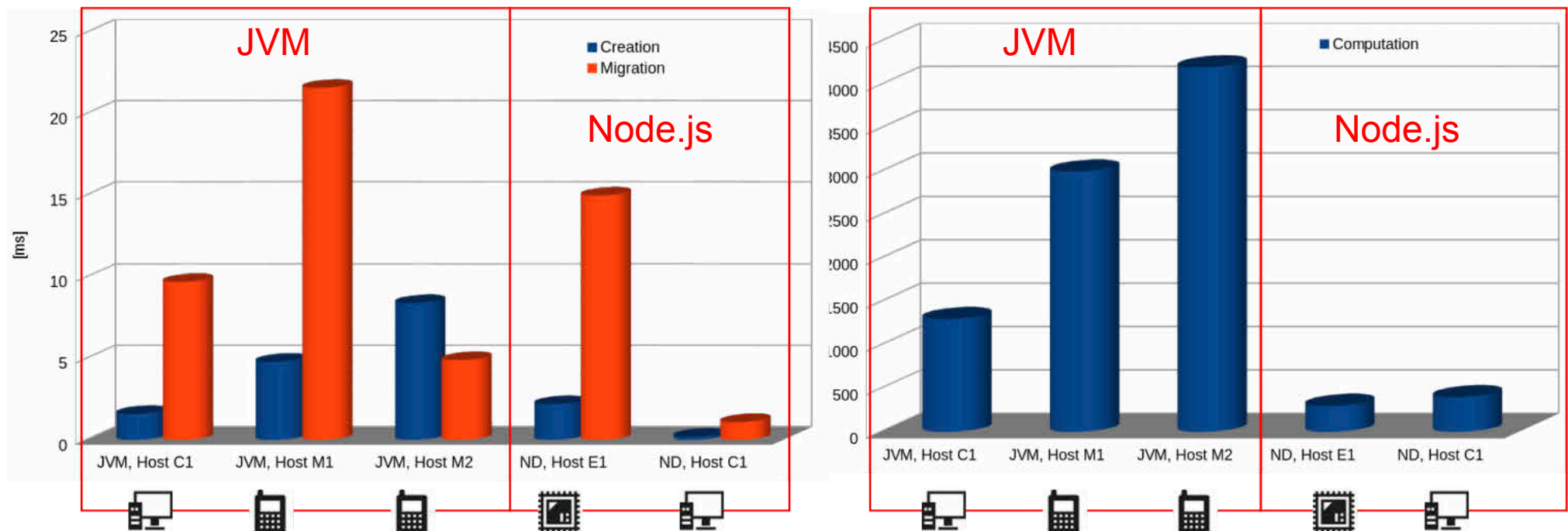
- » *TS*: Tuple Space, *SIG*: Signals, *MOBI*: Mobility, *CONF*: Code Morphing ..
- » For Internet Deployment: + Distributed Organization System (DOS)
- » JS Engines: *node.js*, *jxcore*, *JVM* (Samsung *jerryscript+iotjs*), WEB Browser



JAM: Performance

- » High Performance
 - » Low agent process creation and scheduling latency
 - » Low agent migration latency
 - » High volume agent processing capacity (>1000 agents/JAM)
 - » But depends on JS engine and host
 - ND node.js*: ✓ Performance, *JVM*: ✓ Low-resource

node.js:
JIT Native Code
Compiler
JVM:
Bytecode
Compiler

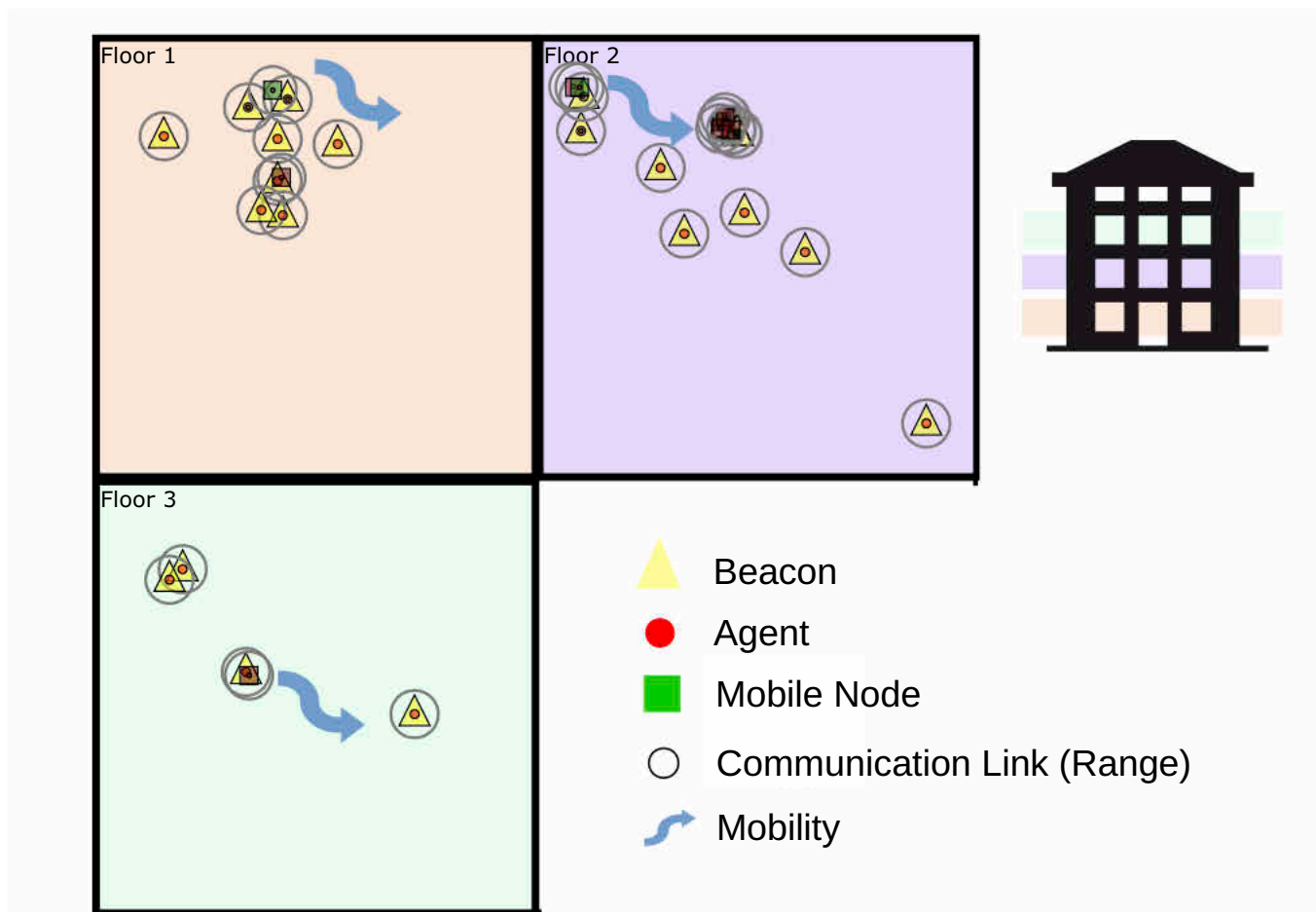


E. Case Study and Simulation: Crowd Sourcing with Agents

NervousNet + Agents + JAM = The Unified Approach

Environment & Scenario

- » Building (Hamburg Congress Center), three floors
- » Each floor populated with stationary beacons and mobile devices



- » Beacons and mobile devices can process agents using JAM
- » Mobile devices can communicate with beacons via Bluetooth
- » Beacons can have Internet access (or not)
- » Agents can migrate to beacons and vice versa

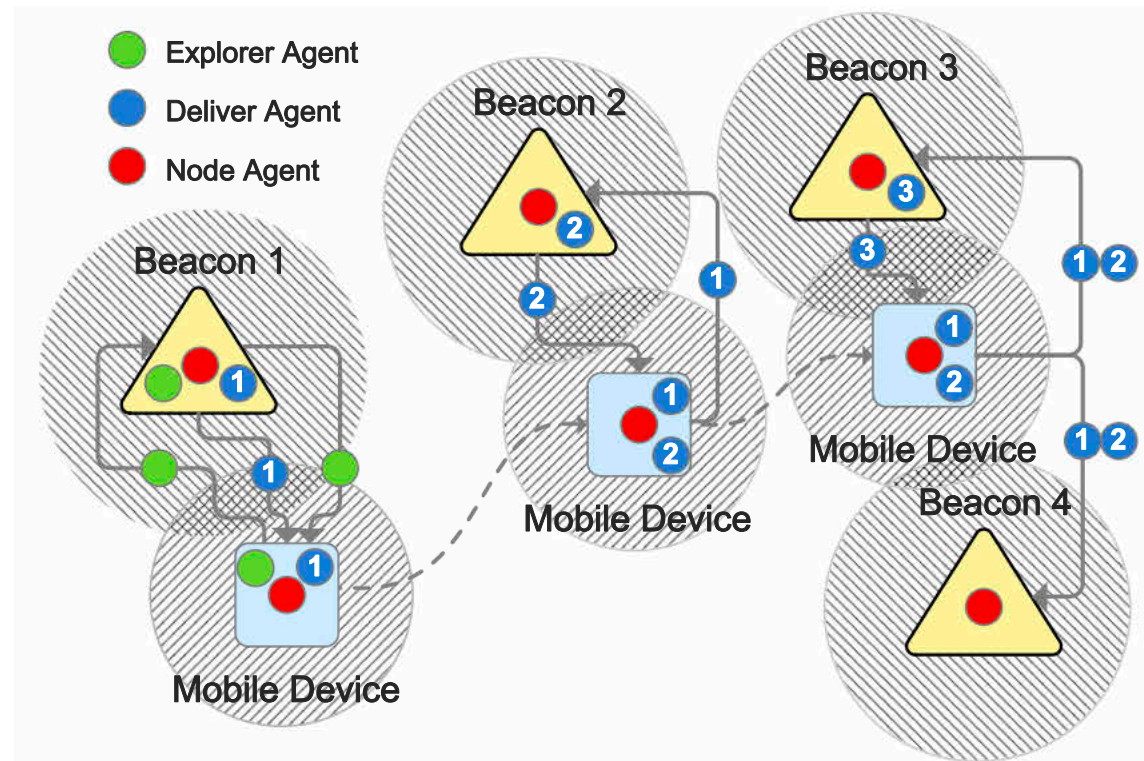
Crowd Sourcing with Agents

- » The goal of the MAS is the self-organized perception, collection and fusion of mobile device sensor data using the Virtual Sensor approach.
- » The collected sensor data (Position, Connectivity c , Acceleration a) is used to recognize specific crowd situations in the building.
- » Virtual Sensor Fusion in ROI of crowd parameters from individual data ➡
Measure of P : Crowd Population, A : Crowd Agitation, F : Crowd Flow

$$\begin{aligned} P(t) &= \frac{1}{k} \sum_{i=1}^{Nc} 1 / (t - t(c_i)) \\ A(t) &= \frac{1}{d} \left(A(t-1) + \frac{1}{k} \sum_{i=1}^{Ns} a_i / (t - t(a_i)) \right) \\ F(t) &= \frac{1}{d} \left(F(t-1) + \sum_{i=1}^{Ns} f_i \right) \end{aligned}$$

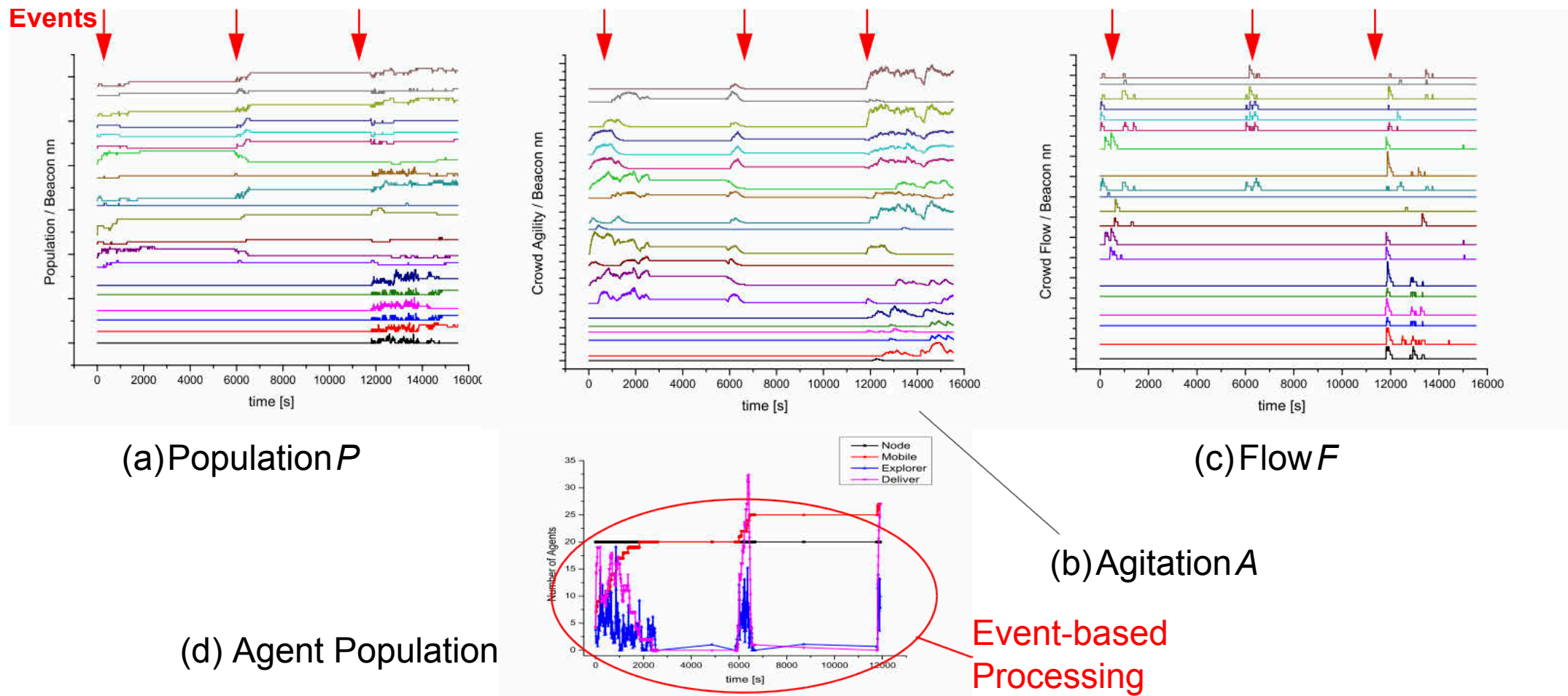
Mobile Devices as Carriers

- » Node agents perform event-based sensor fusion (Virtual Sensor)
- » Explorer Agents are mobile and can visit beacons
- » Deliver agents are mobile and sent by node agents to distribute sensor data using mobile devices.



Simulation & Evaluation

- » Simulation was carried out by the *SEJAM* simulator and NervousNet data from Chaos Communication Congress event, Hamburg, 27.- 30.12.14



F. Conclusions

- » The use-case showed the suitability of the distributed deployment of MAS in the context of the Planetary Nervous system used for crowd sensing.
- » Virtual Sensor approach was implemented with agents
- » The agents can be used to pre-process and reduce the raw sensor data of smart phones in a local ROI, finally distributed across the ROI by agents carried on mobile devices.
- » The agents are represented by mobile JavaScript code (*AgentJS*) that is managed and processed by a modular and portable agent platform *JAM* in a protected environment.
- » *JAM* is implemented entirely in JS, and can be executed on any mobile device.

Announcement

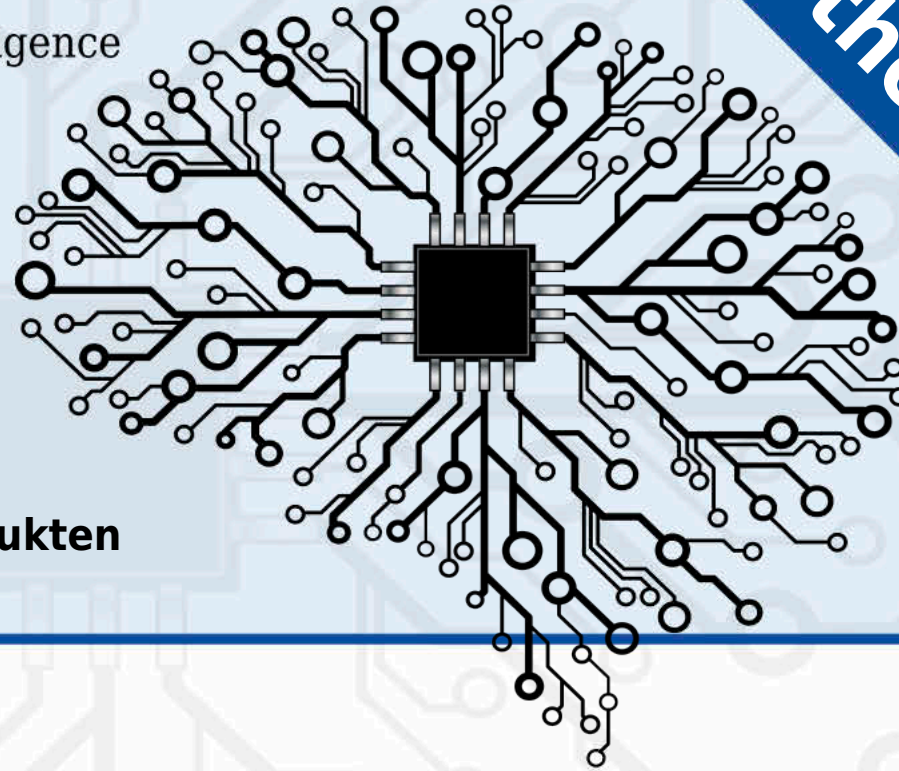


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