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Context and motivation

Why cities and why perception?

- Cities areas are now the predominant *living environment* for the world population
- Important to consider how people feel in and perceive cities
- Which urban features influence perception?
- IoT and Smart City infrastructure to investigate this challenge















Contributions

- A novel data collection process in a real-world urban context
- How data science techniques can improve the quality of smart city data analytics
- Mapping citizen's perception using specific indicators
- Greater understanding of urban qualities by mining spatial correlations

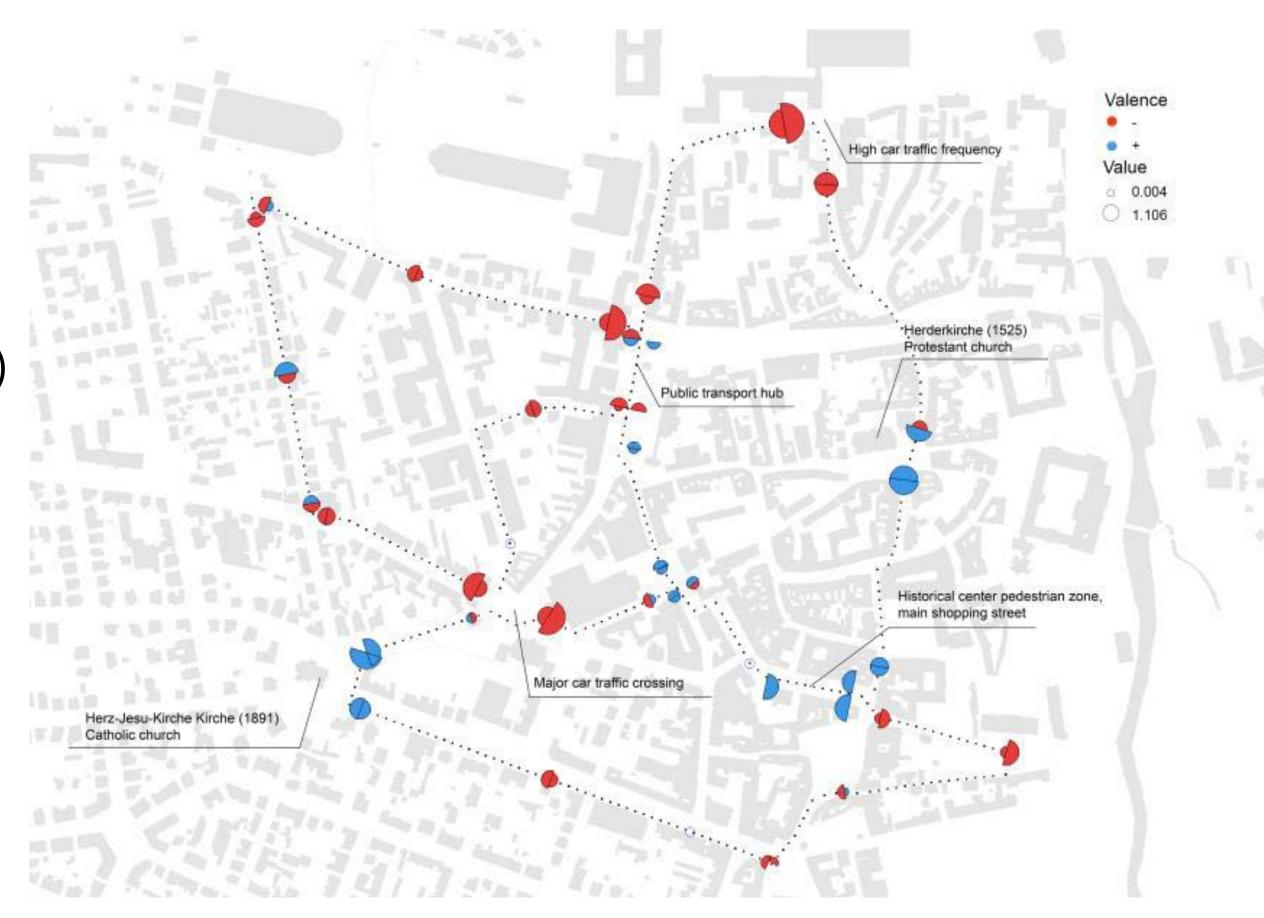




Background

Previous studies from urban planning focus on:

 Explicit perception of urban environments using subjective impression ratings (surveys)







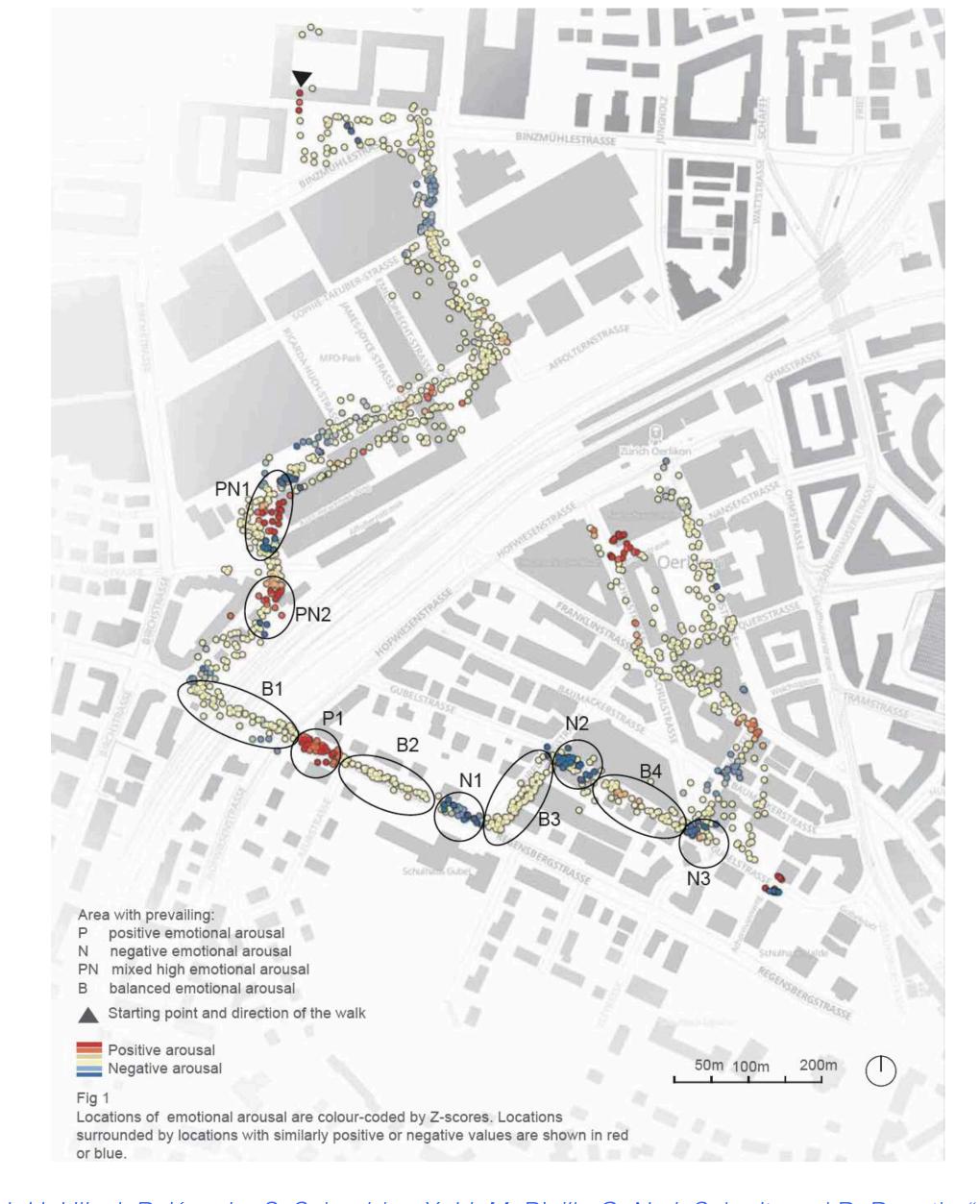




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- Implicit perception of urban environments using biofeedback data



S. I. H. Hijazi, R. Koenig, S. Schneider, X. Li, M. Bielik, G. N. J. Schmit, and D. Donath, "Geostatistical analysis for the study of relationships between the emotional responses of urban walkers to urban spaces," International Journal of E-Planning Research (IJEPR), vol. 5, no. 1, pp. 1-19, 2016.





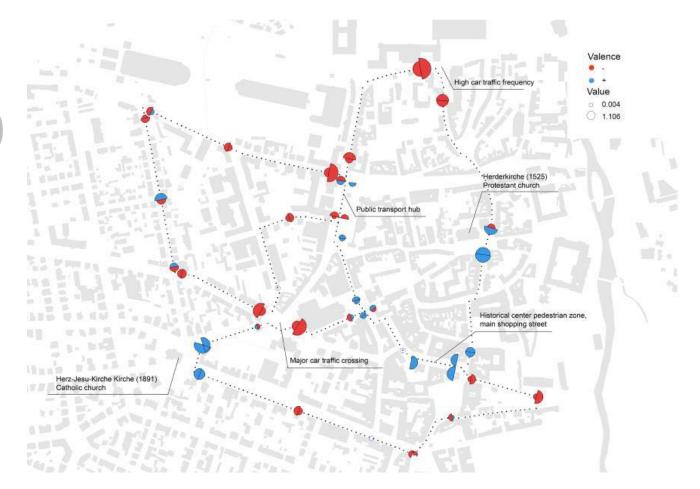


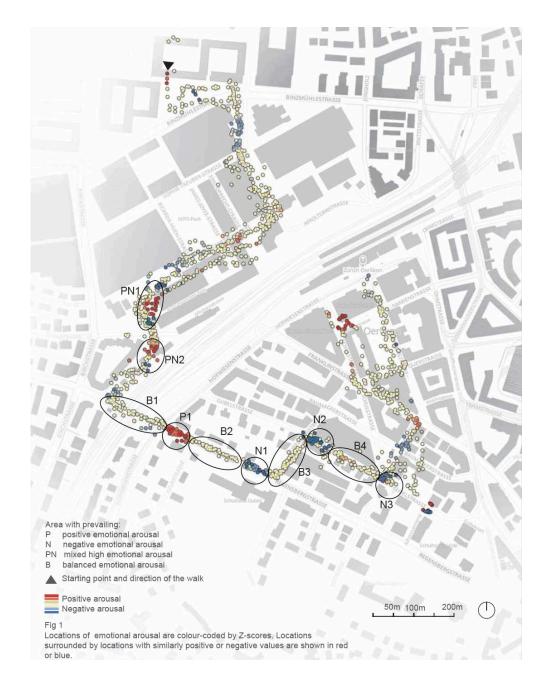
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neither approach consider effects of externalities from the environment such as temp, RH, pollutants, sound, light, etc.







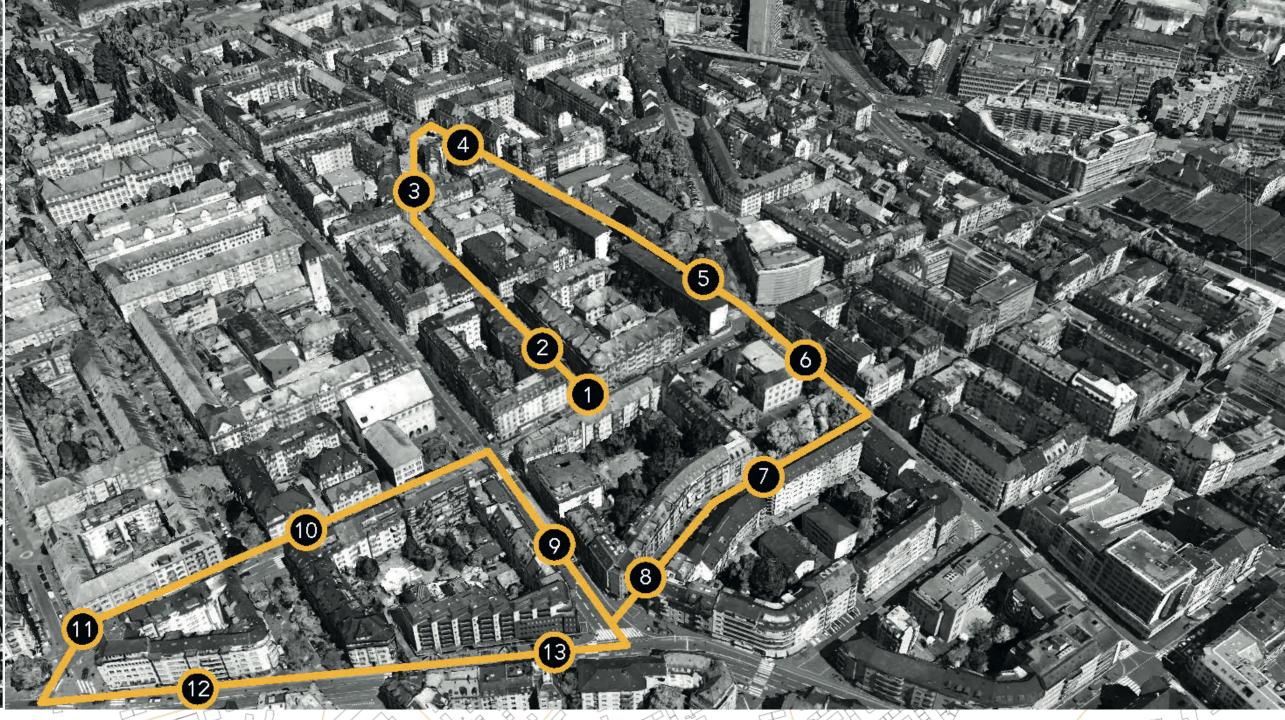




Case study

Zurich, Switzerland





Alt-Wiedikon Zürich

14 survey checkpoints along experimental path







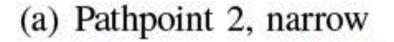
Graphics: Brigitte Clements, brictleme@student.ethz.ch

Experimental setup

Data collection from 37 participants

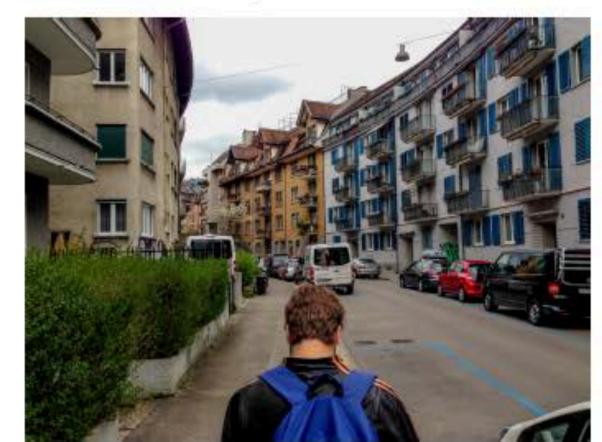
- Investigate perception of:
 - Select urban morphological configurations (narrow, spacious)



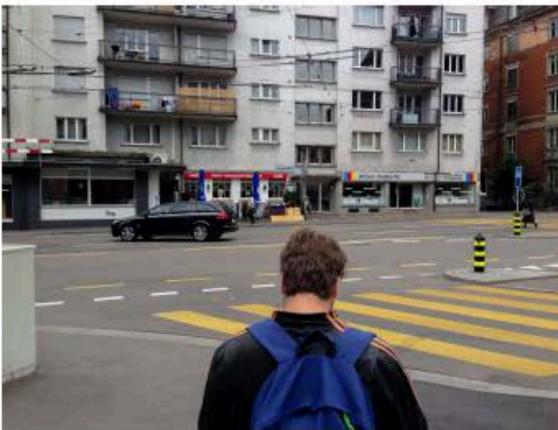




(b) Pathpoint 3, spacious



(e) Pathpoint 7, narrow



(f) Pathpoint 8, spacious





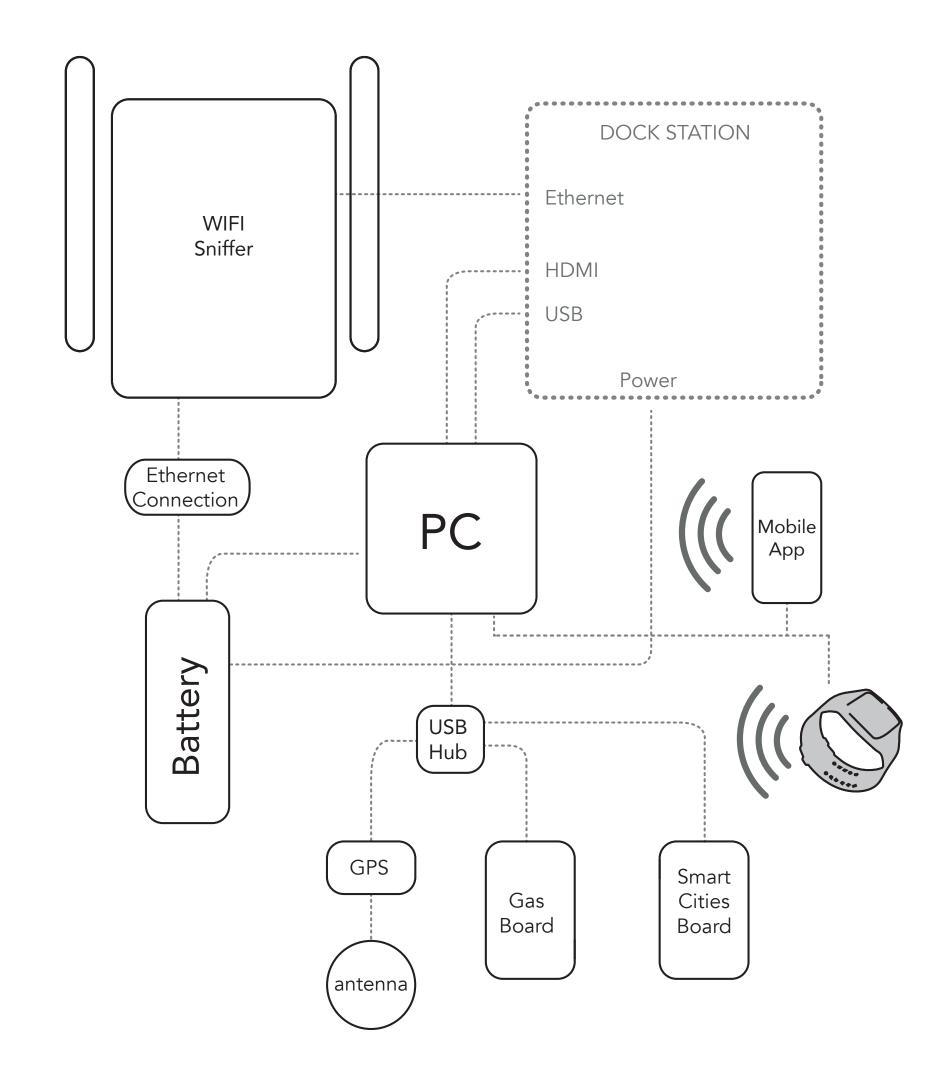


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Experimental setup

Data collection from 37 participants

- Investigate perception of:
 - select urban morphological configurations (narrow, spacious)
 - Environmental conditions as measured by (environmental sensors)



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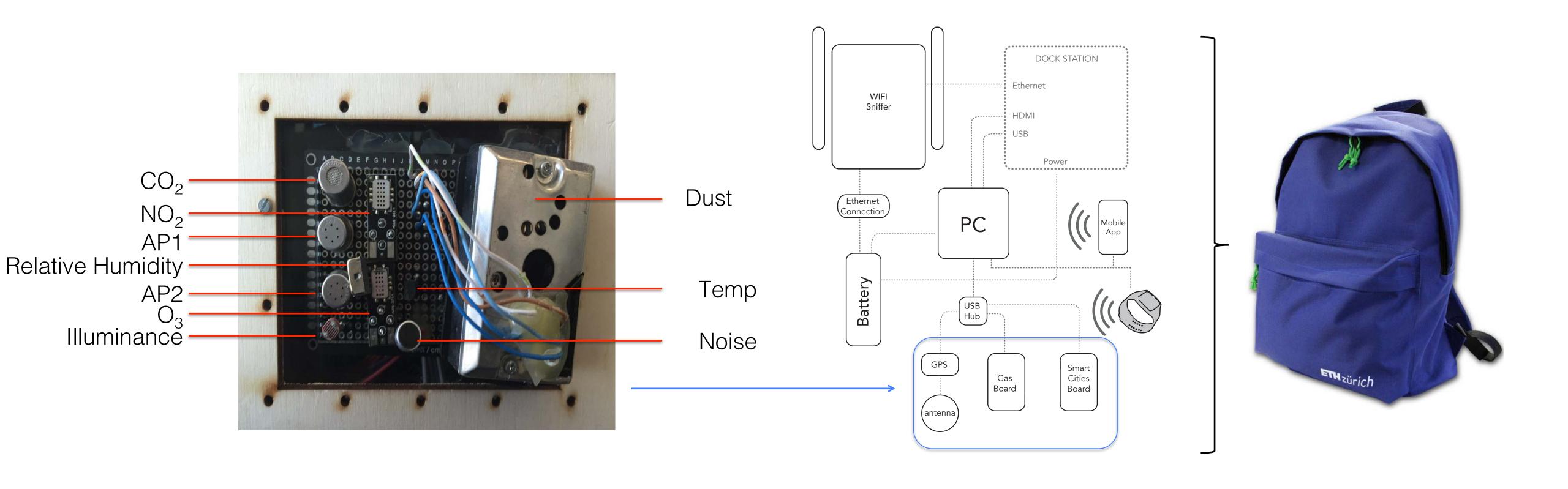






Mobile sensing equipment

Environmental sensors



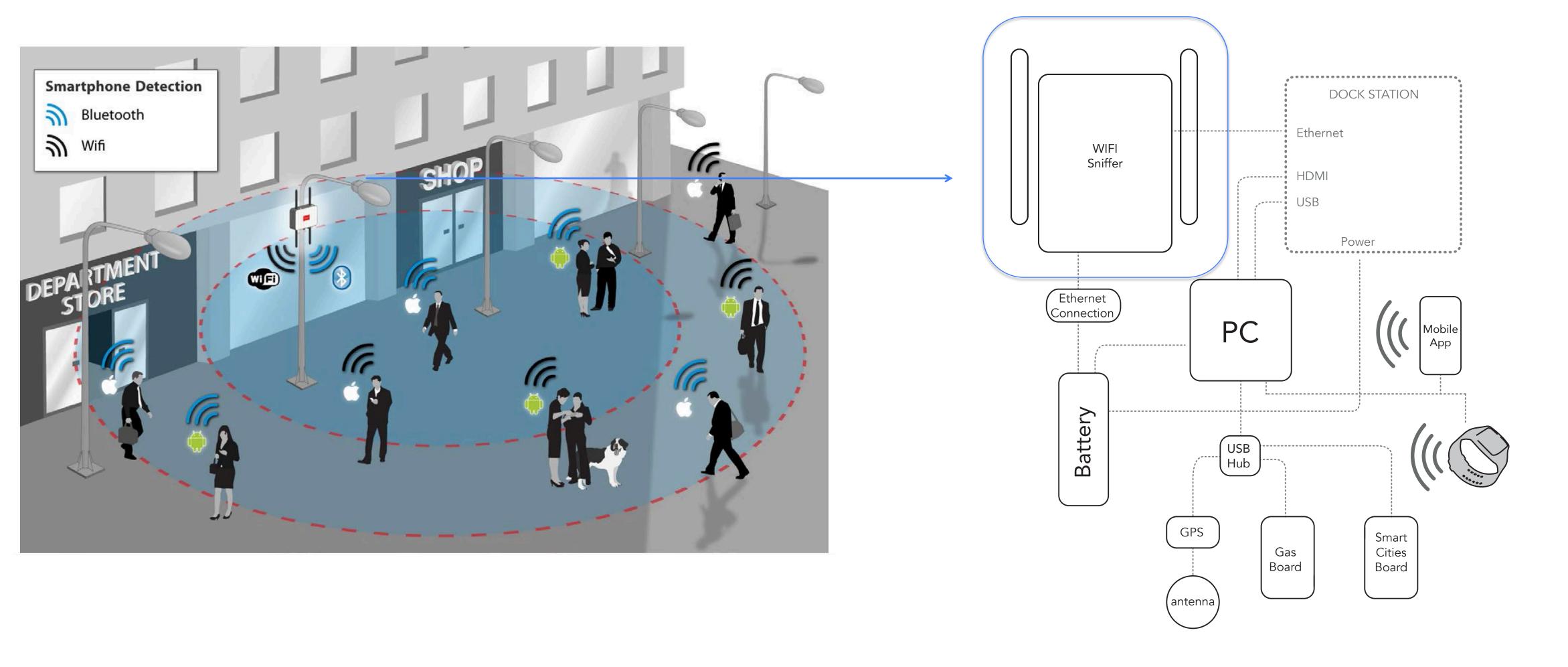






Mobile sensing equipment

Wifi-sniffer









Mobile sensing equipment

Biofeedback sensors

E4 Sensors



PPG Sensor

Photoplethysmography Sensor - Measures Blood Volume Pulse (BVP), from which heart rate, heart rate variability (HRV), and other cardiovascular features may be derived



3-axis Accelerometer

Captures motion-based activity



Event Mark Button

Tags events and correlate them with physiological signals



EDA Sensor (GSR Sensor)

Electrodermal Activity Sensor - Used to measure sympathetic nervous system arousal and to derive features related to stress, engagement, and excitement.



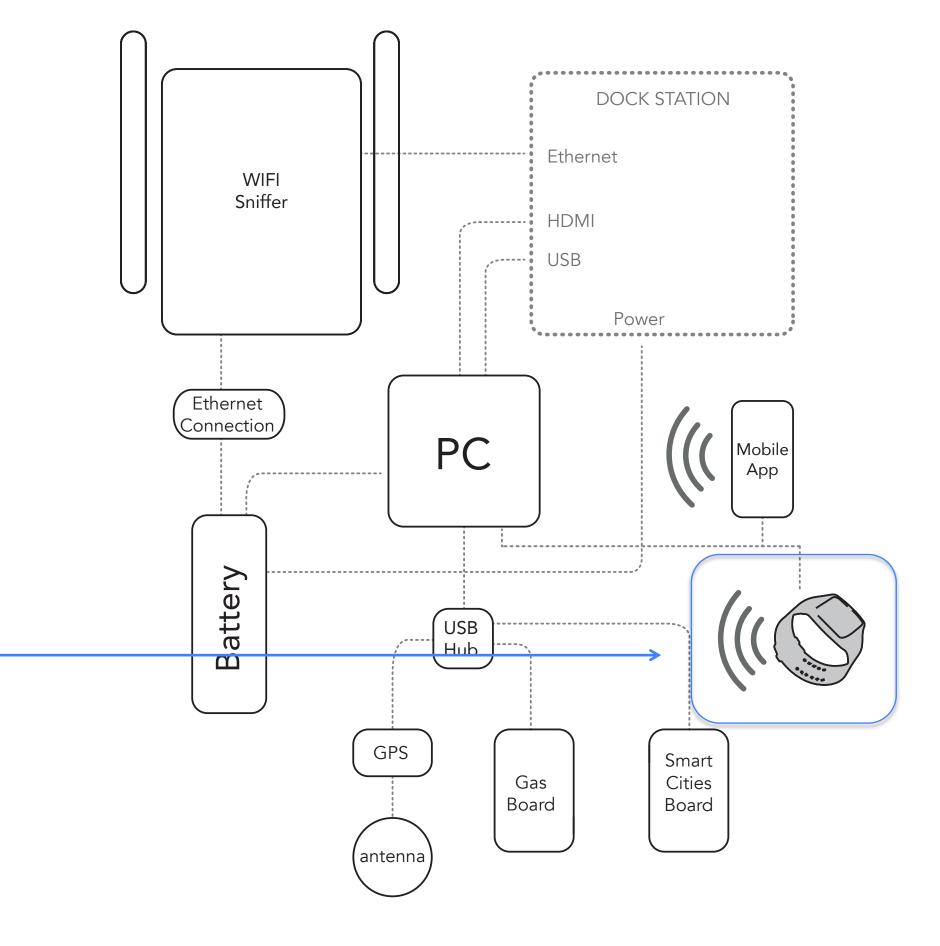
Infrared Thermopile

Reads peripheral skin temperature



Internal Real-Time Clock

Temporal resolution up to 0.2 seconds in streaming mode





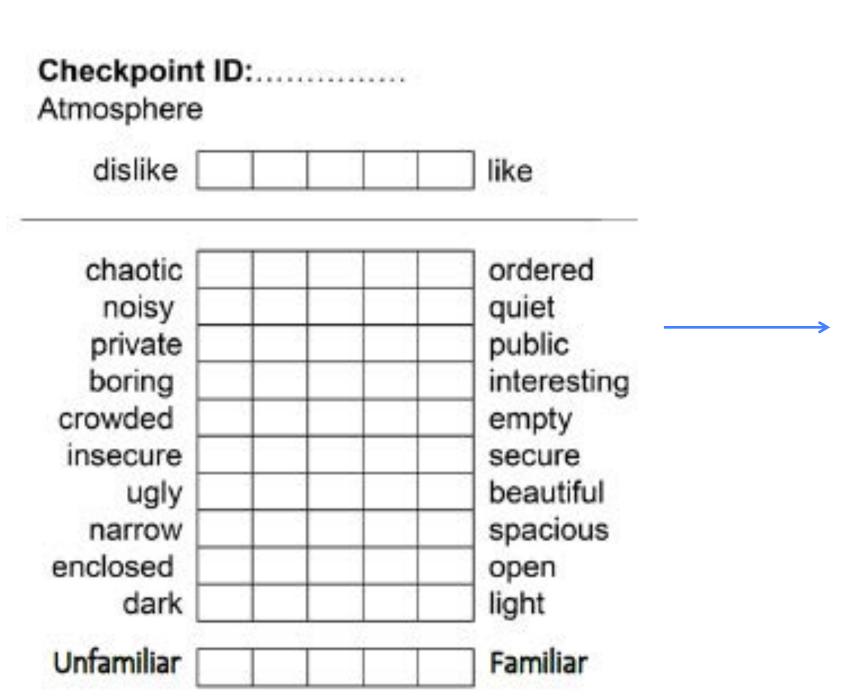




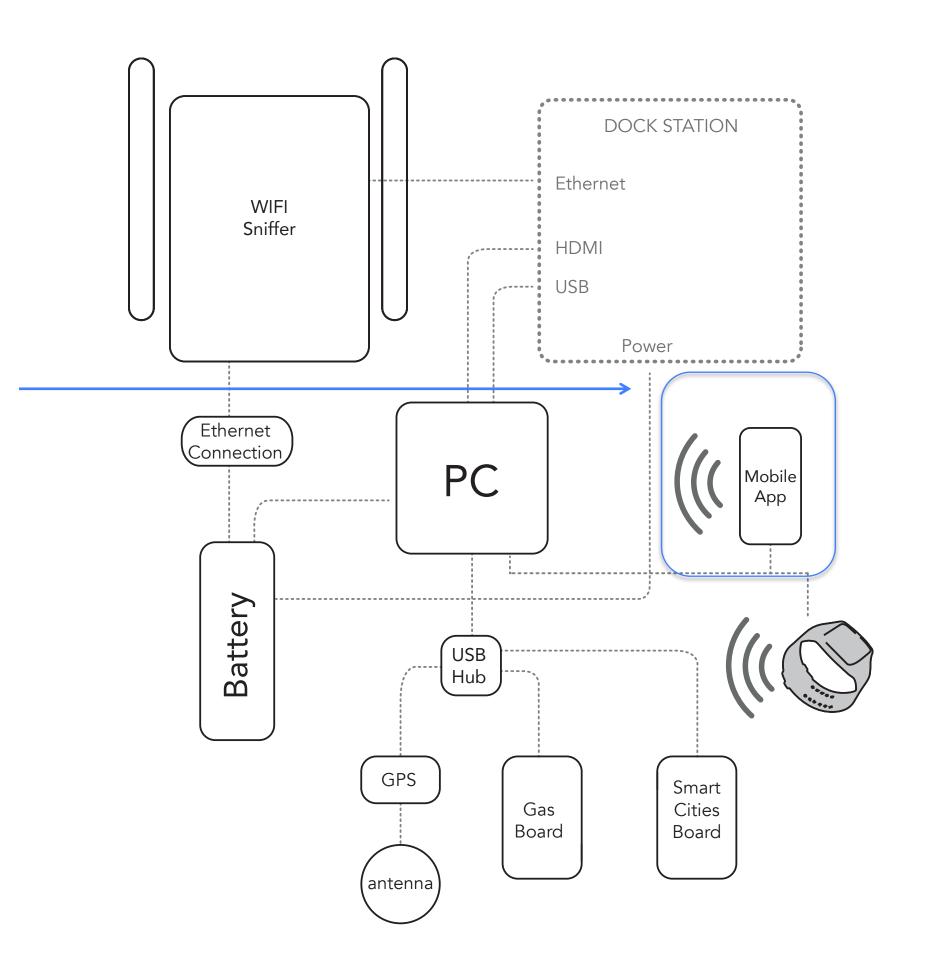


Mobile Sensing equipment

Mobile phone application for virtual sensors













Virtual Sensors

Greenery detection

- Analyzed RGB pixels of Google satellite images using the C++ library "Cimg"
- False positive green pixels excluded by cross referencing neighbor pixels









Virtual Sensors

Appeal, activity, experience



Question #	1	2	3	4	5	6
Question Range	Beautiful Ugly	Empty - Crowded	Familiar - Unfamiliar	Interesting Boring	Light - Dark	Like - Dislike
Used in virtual sensor:	APP	-	APP	ACT	ACT	APP
Question #	7	8	9	10	11	12
Question Range	Open - Enclosed	Ordered Chaotic	Public Private	Quiet Noisy	Secure - Insecure	Spacious Narrow
Used in virtual sensor:	ACT	APP	APP	EXP	EXP	EXP

$$v_j = \sum_{i=1}^k \frac{w_i(q_{i,j}+2)}{k},$$

 v_j =virtual sensor at path point j*k*=the number of questions $q_{i,j}$ = survey responses *i* of range [-2, 2] at path point *j* w_i = weighing factor of sensor i







Virtual Sensor

"Stress level"

E4 Sensors



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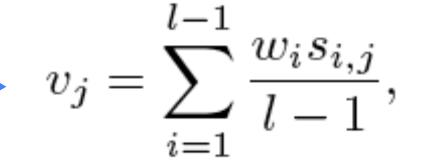
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 v_i =Stress Level

/=number of biofeedback sensors (including HR, T_{BF}, EDA)

 $S_{i,j}$ =normalized biofeedback sensor i at pathpont j

 w_i = weighing factor of sensor i







Overview of all sensors

A total of 19 variables, and 12 measurements and 5 virtual sensors and 2 additional location descriptors

Acronym	Sensor description
PP	Path Point
HR, dHR	Heart Rate
BVP, dBVP	Blood Volume Pressure
EDA, dEDA	Electrodermal Activity
T-BF, dT-BF	Bio Feedback Temperature
S, dS	Sound
D, dD	Dust
T-EN, dT-EN	Environmental Temperature
RH, dRH	Relative Humidity
IL, dIL	Illuminance
ACC, dACC	Acceleration
PD	People Density
LON	Longitude
LAT	Latitude
GR	Greenery
APP	Appeal
ACT	Activity
EXP	Experience
SL	Stress Level







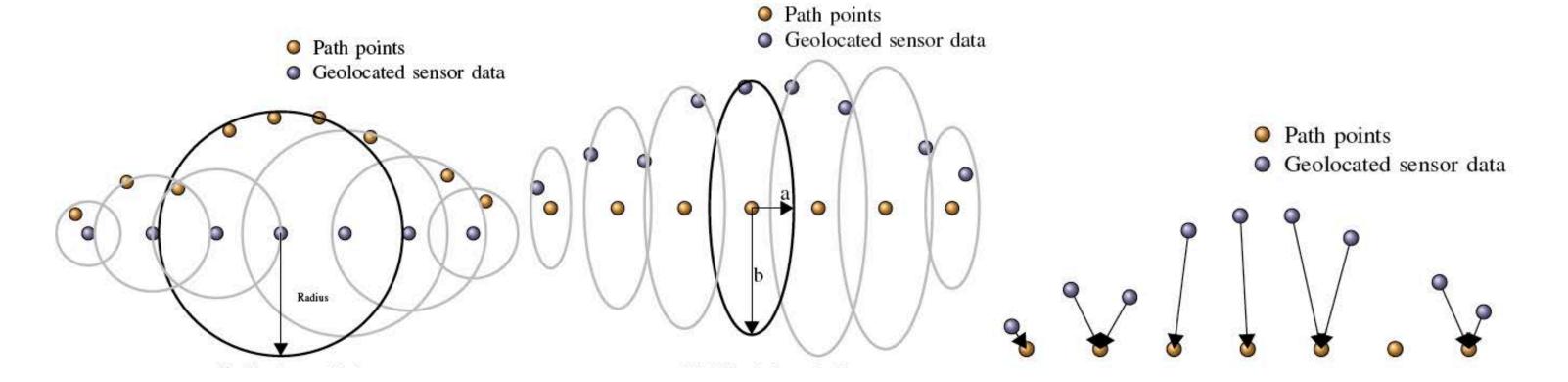
Data processing

Data localization methodology

Circular method

Ellipse method

Minimum distance method



Initial condition: r= 5 meters

Initial condition:

a= 3 meters

b=12 meters





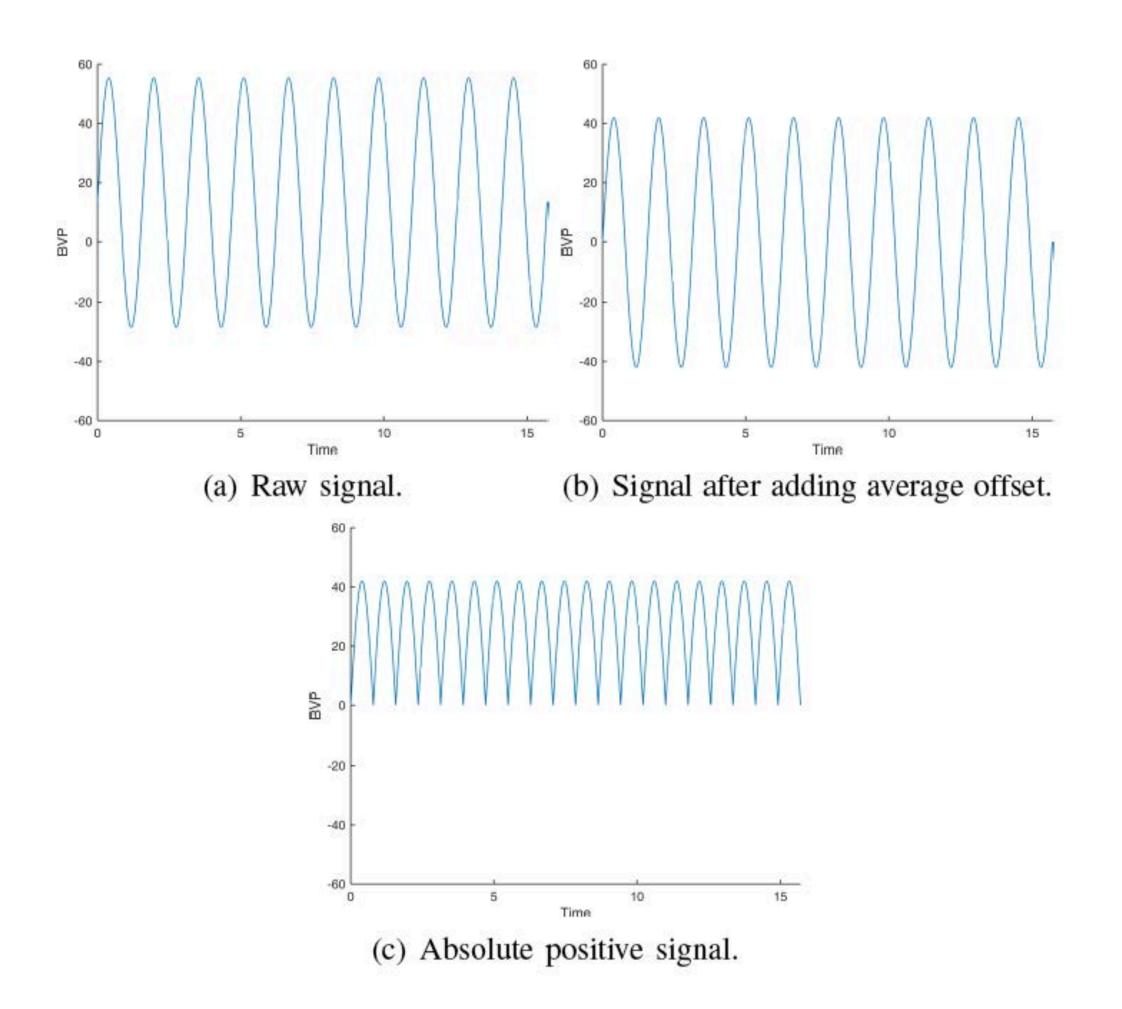




Data Processing

Data integration and frequency reduction and from multiple data sources

Sensor description	Frequency [Hz]
Heart rate (HR)	1
Blood volume pressure (BVP)	64
Electrodermal activity (EDA)	4
Biofeedback temperature (T-BF)	1
Sound level (S)	0.3
Dust (D)	0.3
Environment temperature (T-EN)	1
Relative humidity (RH)	1
Illuminance (IL)	1
People density (PD)	1 (if many), 0.024 (if few)
Longitude (LON)	1
Latitude (LAT)	1
Survey answers	In each of the 14 checkpoints





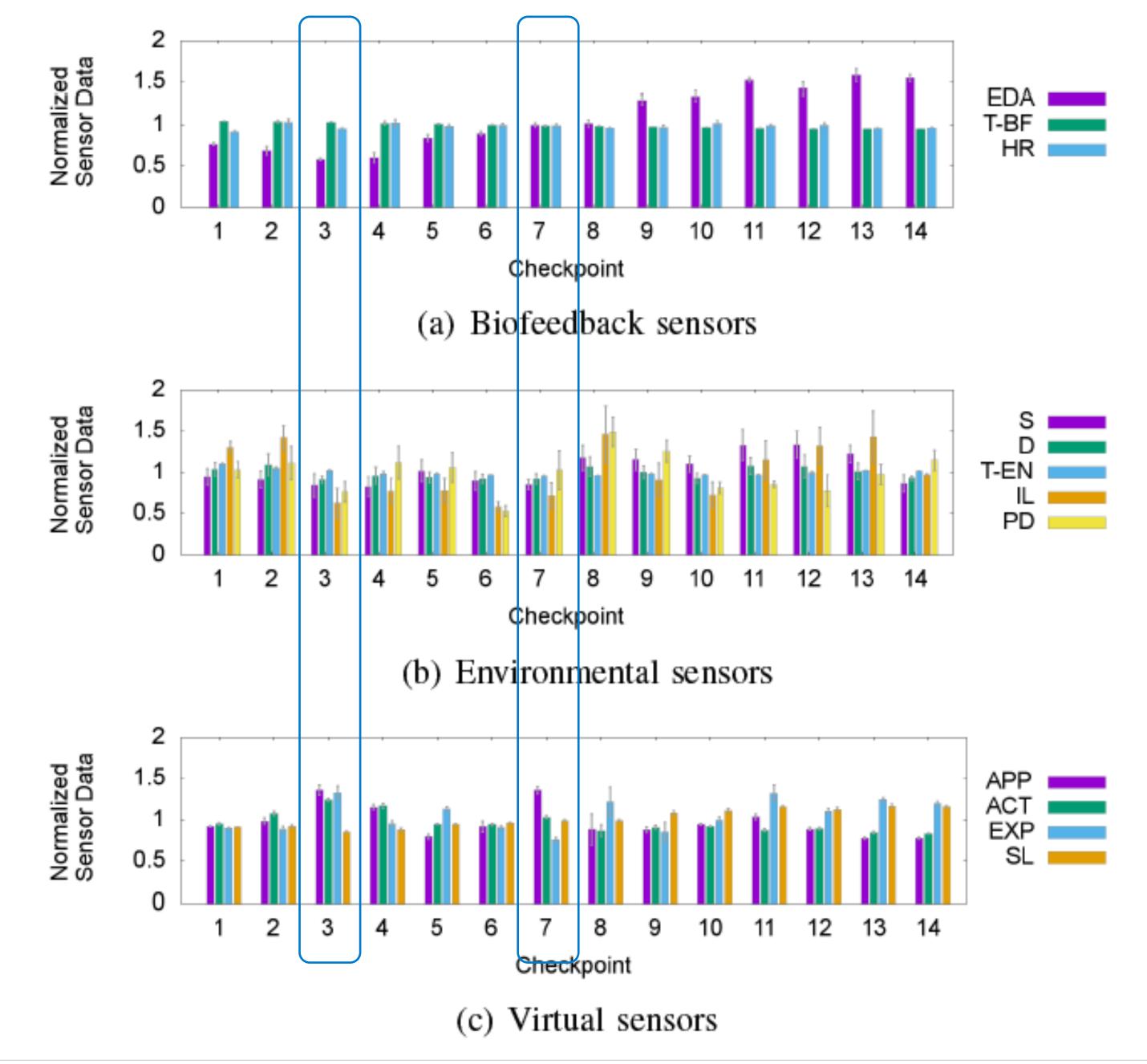




Initial results

Normalized sensor values at each check point

- Most likable check points are 3 and 7
- Increased EDA along the path
 - People sweat more as the experiment progresses
 - It is also noisier from checkpoints 8 to 13





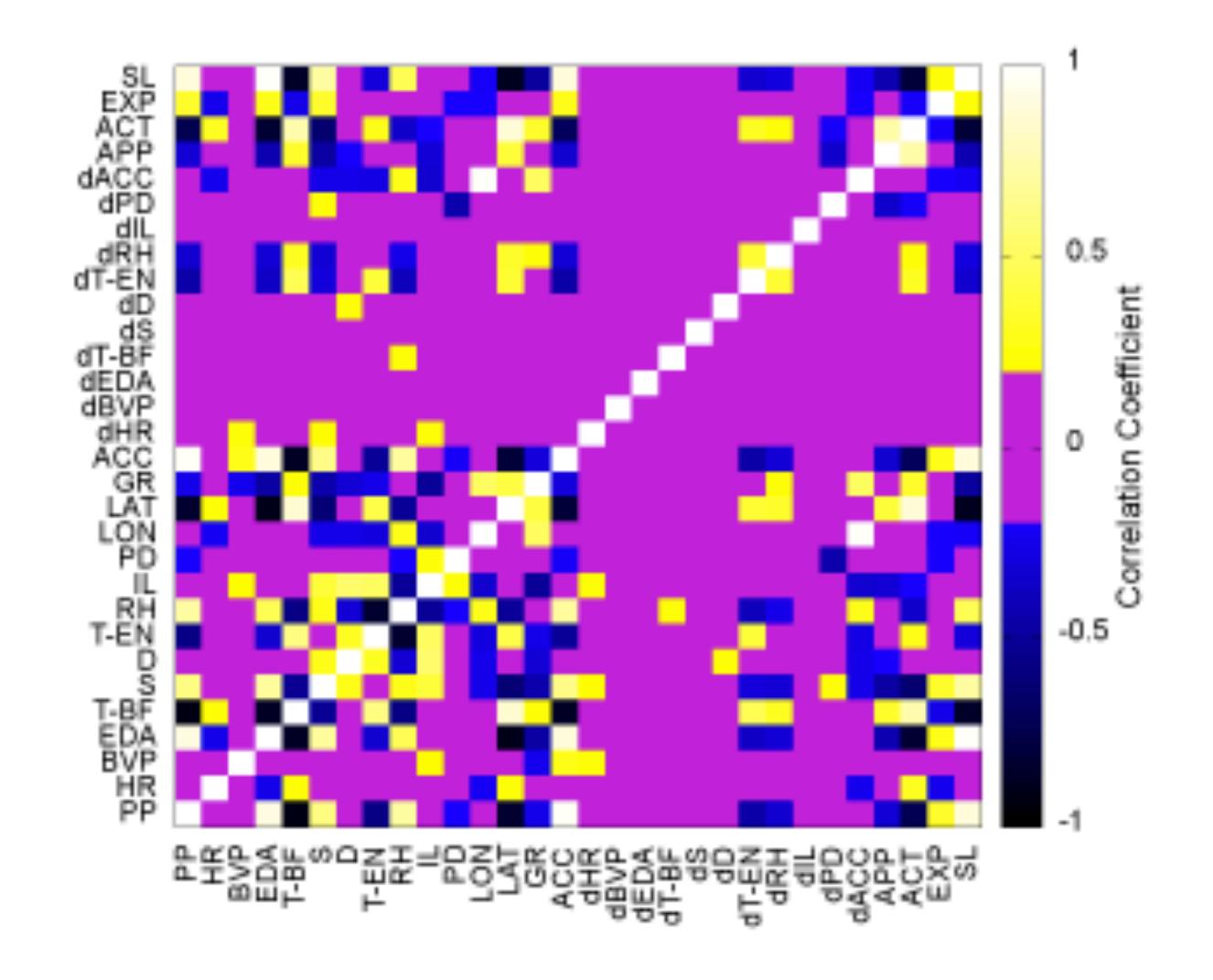




Initial results

Correlation coefficient of all variable pair combinations

- Sound positively correlates with EDA and acceleration:
 - More stress in noisy conditions
 - People walk faster when it's noisy
- Greenery negatively correlates with acceleration and illumination:
 - Greenery indicates that there is more shade
 - Greenery indicates enjoyment (slower walking pace)

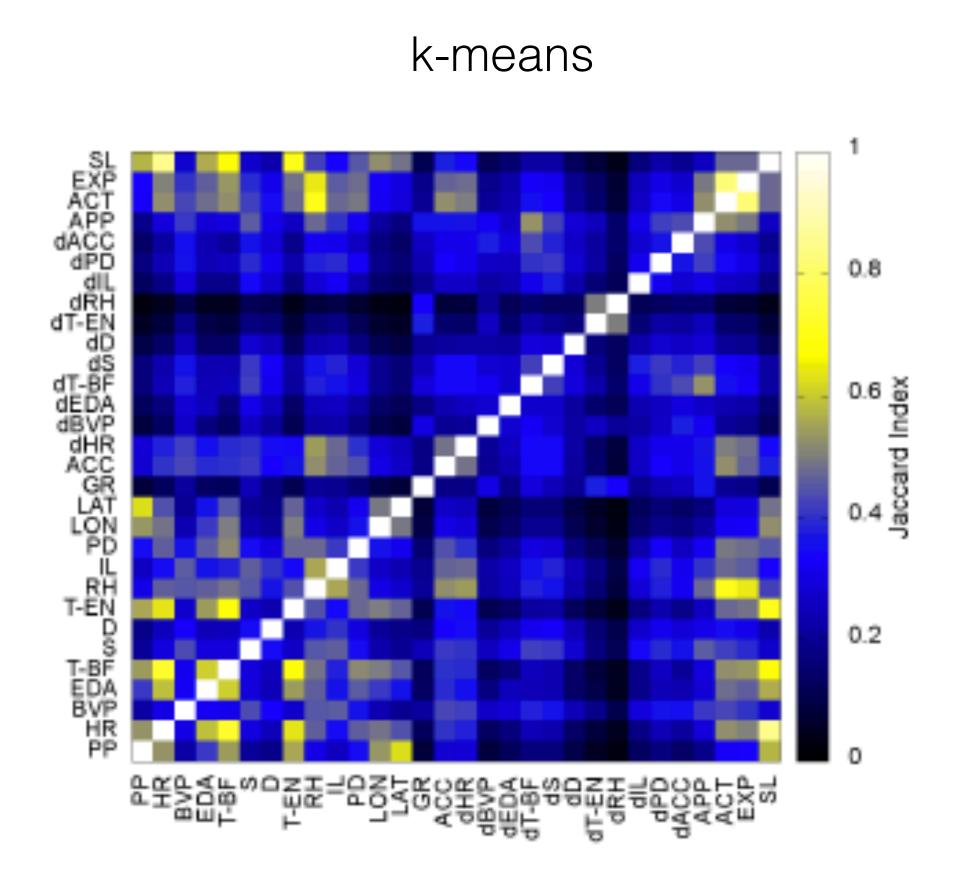




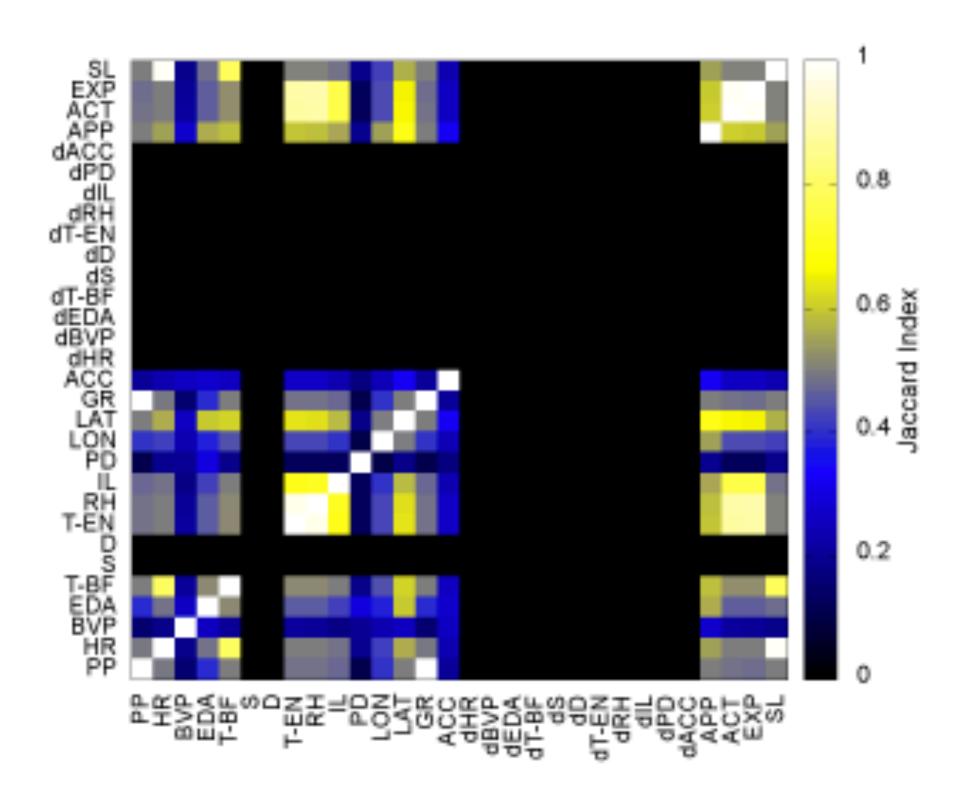


Initial results

Mean jaccard index between all cluster pairs to indicate similarity from k-means and DBSCAN clustering analysis



DBSCAN









Ongoing and future work

Data Analysis of existing data set

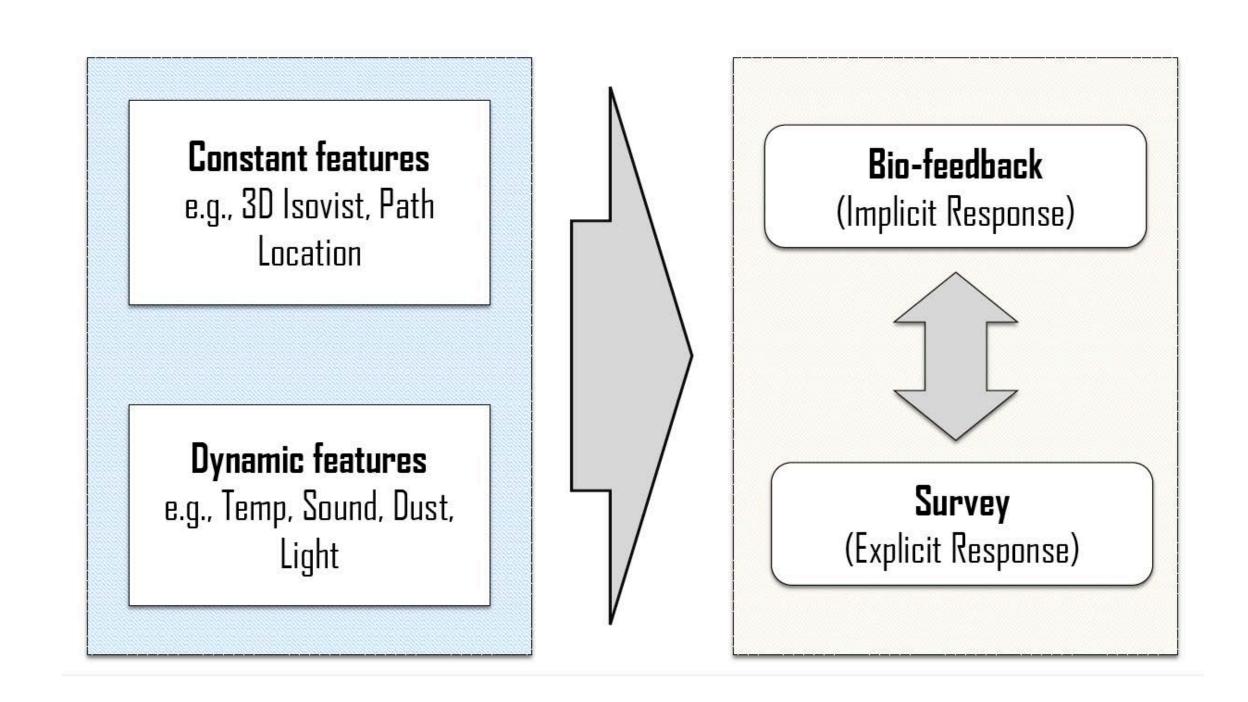
- Automatic clustering using Self Organizing Maps
- Neural Tree or NN: to finds if the participants behavior can be predicted: to perform Feature Selection and Analysis
- Fuzzy Tree or Fuzzy Inference Models: to find inferential (rule based) predictive models to understand if there are certain rule pattern emerge
- Evolutionary Feature Selection of Isovit Features
- Associated Rule Mining: to find pattern in the relationship
- Model survey questions as classification and fuzzy modeling

Future experiments

VR studies with participants to avoid artifacts in the Biofeedback data

Wide-scale implementation

Nervousnet framework for privacy protection of greater number of participants (Evangelos Pournaras)











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Initial Results

Standard deviation of normalized values for checkpoints and path

